# An introduction to Object-Oriented Calculus 

Simon Fortier-Garceau

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(2) The basics of $\varsigma$-calculus
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4 Subtyping
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## Why an object calculus?

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- Interpretations of untyped objects in untyped $\lambda$-calculus is possible...
- But typed object-oriented languages (OOL) are not easily emulated in simply typed $\lambda$-calculus
- Yet, the basics of typed OOL are simple enough...
$\rightarrow$ This suggests investigation of a calculus where objects are used as primitives


## Principles of object-oriented

The four major principles of object-oriented programming (OOP) are :

- Encapsulation: Restricting the manipulation of internal data to the host object methods
- Abstraction: The ability to abstract attributes and implementation details of an object
- Inheritance: The ability of certain classes to call upon method implementations of another class
- Polymorphism : The ability of an object to take many shapes


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... can we combine these with OO principles?


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Ideally, we could interpret objects as processes, or processes as objects, or perhaps, find a different formal system that captures OO style typing and concurrency.

## The basics of $\varsigma$-calculus

## Primitives of the syntax

## Objects and methods

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method with self parameter $x$ and body $b$

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- The letter $\varsigma$ in the method acts as a binder for the self parameter of the object. The self parameter is a reference to "self", that is, the methods' host object.
- When the body $b$ of a method $\varsigma(y) b$ does not use its self parameter $y$, we refer to the method as a field.


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In the case of fields, method invocation and method update are referred as field selection and field update respectively.

## Example of a storage cell

$$
\begin{aligned}
\text { myCell } \triangleq \quad & {[\text { contents }=0,} \\
& \text { get }=\varsigma(s) \text { s.contents }, \\
& \text { set }=\varsigma(s)(\lambda(n)(\text { s.contents } \Leftarrow n))]
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\rightsquigarrow
```


## Example of Movable points

$$
\begin{aligned}
& \text { origin }_{1} \triangleq\left[x=0, m v_{x}=\varsigma(s) \lambda(d x)(s . x \Leftarrow s . x+d x)\right] \\
& \begin{aligned}
\text { origin }_{2} \triangleq[x=0, y=0, & m v_{x}=\varsigma(s) \lambda(d x)(s . x \Leftarrow s . x+d x), \\
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That is, we need a typed system in which any context expecting an origin ${ }_{1}$ object can also accept an origin ${ }_{2}$ object.

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$\rightarrow$ Subtyping

## The first-order $\varsigma$-calculus

## Formal syntax for first-order theory

$A, B, C, D::=$

$$
\begin{aligned}
& \text { Top } \\
& {\left[l_{i}: B_{i} \quad i \in 1 \ldots n\right]} \\
& A \rightarrow B
\end{aligned}
$$

## Types

the biggest type object ( $I_{i}$ distinct) function type

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$$
\begin{aligned}
& x \\
& {\left[l_{i}=\varsigma\left(x_{i}: A_{i}\right) b_{i}^{i \in 1 \ldots n}\right]} \\
& \text { a.l } \\
& \text { a. } / \Leftarrow \varsigma(x: A) b \\
& \lambda(x: A) b \\
& b(a)
\end{aligned}
$$

## Types

the biggest type object ( $I_{i}$ distinct) function type

Terms
variable object ( $I_{i}$ distinct) method invocation method update function application

## Scoping for the first-order calculus

$$
\begin{array}{ll}
F V(x) & \triangleq\{x\} \\
F V(\varsigma(x: A) b) & \triangleq F V(b)-\{x\} \\
F V\left(\left[I_{i}=\varsigma\left(x_{i}: A_{i}\right) b_{i}{ }^{i \in 1 . . . n}\right]\right) & \triangleq \bigcup_{i=1}^{n} F V\left(\varsigma\left(x_{i}: A_{i}\right) b_{i}\right) \\
F V(a . l) & \triangleq F V(a) \\
F V(a . l \Leftarrow \varsigma(x: A) b) & \triangleq F V(a) \cup F V(\varsigma(x: A) b) \\
F V(\lambda(x: A) b) & \triangleq F V(b)-\{x\} \\
F V(b(a)) & \triangleq F V(b) \cup F V(a)
\end{array}
$$

Substitution : $a[b / x]$ is the term $a$ in which all free occurrences of $x$ are substituted for $b$.

## Formal system and judgments

We present a formal system for deriving judgments of the form $E \vdash \mathcal{T}$ where $E$ is an environment and $\mathcal{T}$ is an assertion whose shape depends on the judgment.

- An environment $E$ is a list of assumptions for variables, of the form $x_{1}: A_{1}, \ldots, x_{n}: A_{n}$
- $\emptyset$ stands for the empty environment
- The judgment $E \vdash \diamond$ means that the environment $E$ is well-formed
- The judgment $E \vdash A$ for a type $A$ means that $A$ is a well-formed type in the environment $E$.
- The judgment $E \vdash b: B$ is value typing judgment, stating that the term $b$ has type $B$ in $E$


## Formation rules fragments

Assertions describing how to form well-typed objects and functions :

- $\Delta_{x}$ : environments and term variables
- $\Delta_{K}$ : ground types
- $\Delta_{O b}$ : objects
- $\Delta_{\rightarrow}$ : functions
- $\Delta_{<: ~}$ : subtyping and subsumption
- $\Delta_{<: O b}$ : objects subtyping
- $\Delta_{<: \rightarrow}$ : functions subtyping


## Standard First-Order Fragments

$\Delta_{x}$ : environments and term variables

| $(E n v \emptyset)$ | $(\operatorname{Env} x)$ | $(\operatorname{Val} x)$ |
| :---: | :---: | :---: |
|  | $\frac{E \vdash A \quad x \notin \operatorname{dom}(E)}{E, x: A \vdash \diamond}$ | $\frac{E^{\prime}, x: A, E \vdash \diamond}{E^{\prime}, x: A, E \vdash x: A}$ |

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$\Delta_{K}$ : ground types
(Type Const)
$\frac{E \vdash \diamond}{E \vdash K}$

## Object Fragment

$\Delta_{O b}$ : building objects and object types
(Type Object)
$\frac{E \vdash B_{i} \quad \forall i \in 1 \ldots n \quad\left(l_{i} \text { distinct }\right)}{E \vdash\left[I_{i}: B_{i}{ }^{i \in 1 \ldots n}\right]}$

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\frac{E \vdash B_{i} \quad \forall i \in 1 \ldots n \quad\left(l_{i} \text { distinct }\right)}{E \vdash\left[l_{i}: B_{i}{ }^{i \in 1 \ldots n}\right]}
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(Val Object) (where $\left.A \equiv\left[l_{i}: B_{i}{ }^{i \in 1 \ldots n}\right]\right)$

$$
E, x_{i}: A \vdash b_{i}: B_{i} \quad \forall i \in 1 \ldots n
$$

$$
E \vdash\left[I_{i}=\varsigma\left(x_{i}: A\right) b_{i}{ }^{i \in 1 \ldots n}\right]: A
$$

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(Val Object) (where $\left.A \equiv\left[l_{i}: B_{i}{ }^{i \in 1 \ldots n}\right]\right)$
$E, x_{i}: A \vdash b_{i}: B_{i} \quad \forall i \in 1 \ldots n$
$E \vdash\left[I_{i}=\varsigma\left(x_{i}: A\right) b_{i}{ }^{i \in 1 \ldots n}\right]: A$
(Val Select)
$E \vdash a:\left[l_{i}: B_{i}{ }^{i \in 1 \ldots n}\right] \quad j \in 1 \ldots n$

$$
E \vdash a . l_{j}: B_{j}
$$

## Object Fragment

$\Delta_{O b}$ : building objects and object types
(Type Object)
$\frac{E \vdash B_{i} \quad \forall i \in 1 \ldots n \quad\left(I_{i} \text { distinct }\right)}{E \vdash\left[I_{i}: B_{i}{ }^{i \in 1 \ldots n}\right]}$
(Val Object) (where $\left.A \equiv\left[l_{i}: B_{i}{ }^{i \in 1 \ldots n}\right]\right)$

$$
E, x_{i}: A \vdash b_{i}: B_{i} \quad \forall i \in 1 \ldots n
$$

$$
E \vdash\left[I_{i}=\varsigma\left(x_{i}: A\right) b_{i}{ }^{i \in 1 \ldots n}\right]: A
$$

$($ Val Select $)$
$E \vdash a:\left[l_{i}: B_{i}^{i \in 1 \ldots n}\right] \quad j \in 1 \ldots n$
$E \vdash a . l_{j}: B_{j}$
(Val Update) (where $\left.A \equiv\left[l_{i}: B_{i}{ }^{i \in 1 \ldots n}\right]\right)$

$$
\frac{E \vdash a: A \quad E, x: A \vdash b: B_{j} \quad j \in 1 \ldots n}{E \vdash\left(a . l_{j} \Leftarrow \varsigma(x: A) b\right): A}
$$

## Function Fragment

Abstraction and application mechanisms are used as primitives of the calculus.
$\Delta_{\rightarrow}$ : function types

$$
\begin{gathered}
\text { (Type Arrow) } \\
E \vdash A \quad E \vdash B \\
E \vdash A \rightarrow B
\end{gathered}
$$

(Val Fun)
$E \vdash \lambda(x: A) b: A \rightarrow B$
(Val Appl)
$E \vdash b: A \rightarrow B \quad E \vdash a: A$
$E \vdash b(a): A$

## Subtyping

## Subtyping fragment

$\Delta_{<: ~}$ : subtypes (" $A<: B$ " means $A$ is a subtype of $B$ )

$$
\begin{aligned}
& \text { (Sub Refl) } \\
& \text { (Sub Trans) } \\
& \text { (Val Subsumption) } \\
& \text { (Type Top) } \\
& \text { (Sub Top) }
\end{aligned}
$$

## Object and function subtypes

$\Delta_{<: O b}:$ Object subtypes

> (Sub Object)

$$
\frac{E \vdash B_{i} \quad \forall i \in 1 \ldots n+m \quad\left(I_{i} \text { distinct }\right)}{E \vdash\left[l_{i}: B_{i} \in 1 \ldots n+m\right]<:\left[l_{i}: B_{i}^{i \in 1 \ldots n}\right]}
$$

## Object and function subtypes

$\Delta_{<: O b}$ : Object subtypes
(Sub Object)

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\frac{E \vdash B_{i} \quad \forall i \in 1 \ldots n+m \quad\left(l_{i} \text { distinct }\right)}{E \vdash\left[l_{i}: B_{i} i \in 1 \ldots n+m\right]<:\left[l_{i}: B_{i}{ }^{i \in 1 \ldots n}\right]}
$$

$\Delta_{<: \rightarrow}$ : Function subtypes

$$
\begin{gathered}
\text { (Sub Arrow) } \\
E \vdash A^{\prime}<: A \quad E \vdash B<: B^{\prime} \\
E \vdash A \rightarrow B<: A^{\prime} \rightarrow B^{\prime}
\end{gathered}
$$

(contravariant in the domain, covariant in the codomain)

## Example of typed Movable points

$$
\begin{aligned}
& A \triangleq\left[x: \text { Real, } m v_{x}: \text { Real } \rightarrow A\right] \\
& B \triangleq\left[x: \text { Real, } y: \text { Real, } m v_{x}: \text { Real } \rightarrow B, m v_{y}: \text { Real } \rightarrow B\right] \\
& \text { origin }_{1} \triangleq\left[x=0, m v_{x}=\varsigma(s) \lambda(d x)(s \cdot x \Leftarrow s \cdot x+d x)\right]: A \\
& \text { origin }_{2} \triangleq\left[x=0, y=0, m v_{x}=\varsigma(s) \lambda(d x)(s \cdot x \Leftarrow s \cdot x+d x),\right. \\
& \left.\quad m v_{y}=\varsigma(s) \lambda(d y)(s . y \Leftarrow s \cdot y+d y)\right]: B
\end{aligned}
$$

## Movable points

$$
\begin{gathered}
A \triangleq[x: \text { Real, mv }: \text { Real } \rightarrow A] \\
B \triangleq\left[x: \text { Real, } y: \text { Real, mv } v_{x}: \text { Real } \rightarrow B, m v_{y}: \text { Real } \rightarrow B\right] \\
\text { origin }_{1} \triangleq\left[x=0, m v_{x}=\varsigma(s) \lambda(d x)(s \cdot x \Leftarrow s \cdot x+d x)\right]: A \\
\text { origin }_{2} \triangleq\left[x=0, y=0, m v_{x}=\varsigma(s) \lambda(d x)(s \cdot x \Leftarrow s \cdot x+d x)\right. \\
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\text { origin }_{1} \triangleq\left[x=0, m v_{x}=\varsigma(s) \lambda(d x)(s \cdot x \Leftarrow s \cdot x+d x)\right]: A \\
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\left.\quad m v_{y}=\varsigma(s) \lambda(d y)(s \cdot y \Leftarrow s \cdot y+d y)\right]: B
\end{gathered}
$$

- We have $B<: A$. Thus, by subsumption, origin2 : $A$.


## Movable points

$$
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- origin1 $\leftrightarrow$ origin2 : $A$, but not origin1 $\leftrightarrow$ origin2 : $B$


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\end{aligned}
$$

- We have $B<: A$. Thus, by subsumption, origin2 : $A$.
- origin1 $\leftrightarrow$ origin2 : $A$, but not origin1 $\leftrightarrow$ origin2 : $B$
- Once origin2 is subsumed to the type $A$, we cannot invoke the methods $m v_{y}$ or $y$ on origin . $^{\text {. }}$

Example : if $B \triangleq\left[x:\right.$ Real, $y:$ Real, $m v_{x}:$ Real $\rightarrow B, m v_{y}:$ Real $\left.\rightarrow A\right]$, then origin ${ }_{2} \cdot m v_{y}(4)$ has type $A$, which means that I cannot derive (origin ${ }_{2} \cdot m v_{y}(4)$ ).mv $v_{y}$ as a typed value in the formal system.

## Cells and encapsulation

A RomCell is a storage cell that can only be read.

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Let's consider storage for natural numbers (Nat) :
PrivateCell $\triangleq[$ contents : Nat, get : Nat, set : Nat $\rightarrow$ RomCell ] PromCell $\triangleq[$ get : Nat, set : Nat $\rightarrow$ RomCell $]$
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We get PrivateCell $<$ : PromCell $<$ : RomCell.

## Cells and encapsulation

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PromCell \triangleq [ get : Nat, set:Nat }->\mathrm{ RomCell ]
RomCell }\triangleq[get : Nat
```


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```
PrivateCell \(\triangleq[\) contents : Nat, get : Nat, set : Nat \(\rightarrow\) RomCell ]
PromCell \(\triangleq[\) get : Nat, set : Nat \(\rightarrow\) RomCell \(]\)
RomCell \(\triangleq[g e t: N a t]\)
myCell : PrivateCell \(\triangleq \quad[\) contents \(=0\),
get \(=\varsigma(s\) : PrivateCell)s.contents,
set \(=\varsigma(s:\) PrivateCell \()(\lambda(n)(s\).contents \(\Leftarrow n))]\)
```

We can use subsumption to get myCell:PromCell and hide contents.

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```
PrivateCell \triangleq [ contents : Nat, get : Nat, set : Nat }->\mathrm{ RomCell ]
PromCell \triangleq [ get : Nat, set : Nat }->\mathrm{ RomCell ]
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get = s(s:PrivateCell)s.contents,
set = }(s:\mathrm{ PrivateCell )}(\lambda(n)(s.contents \Leftarrown))
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The subtyping PrivateCell $<$ : RomCell is required to type the set method because its body has a PrivateCell method, whereas the expected return type is RomCell.

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```

We can use subsumption to get myCell:PromCell and hide contents.

The subtyping PrivateCell $<$ : RomCell is required to type the set method because its body has a PrivateCell method, whereas the expected return type is RomCell.
$s:$ PrivateCell $\vdash \lambda(n:$ Nat $)($ s.contents $\Leftarrow n):$ Nat $\rightarrow$ PrivateCell $<$ :
$N a t \rightarrow$ RomCell by covariance on codomain types

## Cells and encapsulation

```
PrivateCell \(\triangleq[\) contents : Nat, get : Nat, set : Nat \(\rightarrow\) RomCell ]
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```

Now, we can show that :

## Cells and encapsulation

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myCell.set $:$ Nat $\rightarrow$ RomCell

## Cells and encapsulation

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myCell.set : Nat $\rightarrow$ RomCell
myCell.set(3) : RomCell
(can't write myCell.set(3).contents or myCell.set(3).set)

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PrivateCell \(\triangleq[\) contents : Nat, get : Nat, set : Nat \(\rightarrow\) RomCell ]
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myCell.set : Nat $\rightarrow$ RomCell
myCell.set(3) : RomCell
(can't write myCell.set(3).contents or myCell.set(3).set)
myCell.set(3).get : Nat $\rightsquigarrow 3$ : Nat

## Classes and inheritance

## Classes

- Given an object type $A \equiv\left[\iota_{i}: B_{i}{ }^{i \in 1 \ldots n}\right]$ :
$\operatorname{Class}(A) \triangleq\left[\right.$ new $\left.: A, l_{i}: A \rightarrow B_{i}{ }^{i \in 1 \ldots n}\right]$
is the type of classes generating objects of type $A$.


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$$

is the type of classes generating objects of type $A$.

- These classes are objects of the form :

$$
\begin{aligned}
{[\text { new }} & =\varsigma(z: C l a s s(A))\left(\left[l_{i}=\varsigma(s: A) z . l_{i}(s)^{i \in 1 \ldots n}\right]\right), \\
l_{i} & \left.=\lambda(s: A) b_{i} i \in 1 \ldots n\right] .
\end{aligned}
$$

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l_{i} & \left.=\lambda(s: A) b_{i} i \in 1 \ldots n\right] .
\end{aligned}
$$

- The methods of a class are called pre-methods, whose $\lambda$ binders are meant to be replaced with $\varsigma$ binders, that will link an instantiated object to its methods.


## Inheritance

Inheritance is the re-use of pre-methods from a class within another class.

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Inheritance is the re-use of pre-methods from a class within another class.

An ad-hoc criteria for re-use :
$\operatorname{Class}\left(A^{\prime}\right)$ may inherit from $\operatorname{Class}(A)$ iff $A^{\prime}<: A$

## Inheritance

For example, consider $A^{\prime} \equiv\left[l_{i}: B_{i}{ }^{i \in 1 \ldots n+m}\right]<: A \equiv\left[l_{i}: B_{i}{ }^{i \in 1 \ldots n}\right]$ and the following classes :

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$$
\begin{aligned}
c: \operatorname{Class}(A) \triangleq[\text { new } & =\varsigma(z: \operatorname{Class}(A))\left(\left[l_{i}=\varsigma(s: A) z . l_{i}(s)^{i \in 1 \ldots n}\right]\right), \\
l_{i} & \left.=\lambda(s: A) b_{i} \in 1 \ldots n\right]
\end{aligned}
$$

$c^{\prime}: \operatorname{Class}\left(A^{\prime}\right) \triangleq\left[n e w=\varsigma\left(z: \operatorname{Class}\left(A^{\prime}\right)\right)\left(\left[I_{1}=\varsigma\left(s: A^{\prime}\right) z . l_{i}(s)^{i \in 1 \ldots n+m}\right]\right)\right.$,

$$
\begin{aligned}
& I_{1}=\lambda\left(s: A^{\prime}\right) b_{1}^{\prime}, \\
& I_{j}=c . I_{j} \quad j \in \ldots n \\
& \left.I_{k}=\lambda\left(s: A^{\prime}\right) b_{k} \quad k \in n+1 \ldots n+m\right]
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c: \operatorname{Class}(A) \triangleq\left[\begin{array}{rl}
n e w & = \\
l_{i} & =\lambda\left(z: \operatorname{Class}(A) b_{i} i \in 1 \ldots n\right] \\
c^{\prime}: \operatorname{Class}\left(A^{\prime}\right) \triangleq\left[\begin{array}{l}
\text { new }
\end{array}\right. & =\varsigma\left(z: \operatorname{Class}\left(A^{\prime}\right)\right)\left(\left[l_{1}=\varsigma\left(s: A^{\prime}\right) z . l_{i}(s)^{i \in 1 \ldots n+m}\right]\right), \\
I_{1} & =\lambda\left(s: A^{\prime}\right) b_{1}^{\prime}, \\
l_{j} & =c . l_{j}, l_{i}(s)^{i \in 1 \ldots n}, \\
I_{k} & \left.=\lambda\left(s: A^{\prime}\right) b_{k} \quad k \in n+1 \ldots n+m\right]
\end{array}\right.
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- $c^{\prime}$ overrides the pre-method $I_{1}$


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& I_{1}=\lambda\left(s: A^{\prime}\right) b_{1}^{\prime}, \\
& l_{j}=c . l_{j} \quad j \in 2 \ldots n, \\
& \left.I_{k}=\lambda\left(s: A^{\prime}\right) b_{k} \quad k \in n+1 \ldots n+m\right]
\end{aligned}
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- $c^{\prime}$ overrides the pre-method $I_{1}$
- $c^{\prime}$ inherits the pre-methods $l_{j}$ with $j \in 2 \ldots n$ from $c$ (c. $l_{j}: A \rightarrow B<: A^{\prime} \rightarrow B$ by contravariance on $A^{\prime}<: A$ ).


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- $c^{\prime}$ has some new pre-methods of it's own $k \in n+1 \ldots n+m$


## Polymorphism

## A class that instantiates polymorphic cells

Private cell type with a dependency on a type variable $X$ :

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PrivateCell $\{X\} \triangleq[$ contents : $X$, get $: X$, set : $X \rightarrow$ RomCell ]
Abstraction on the type : $\forall(X)$ PrivateCell $\{X\}$
Polymorphic class type for cells: Class $(\forall(X)$ PrivateCell $\{X\}) \triangleq$
[ new : $\forall(X)$ PrivateCell $\{X\}$,
contents: $\forall(X)($ PrivateCell $\{X\} \rightarrow X)$,
get : $\forall(X)($ PrivateCell $\{X\} \rightarrow X)$,
set $: \forall(X)($ PrivateCell $\{X\} \rightarrow X \rightarrow \operatorname{RomCell}\{X\})]$

## A class that instantiates polymorphic cells

Polymorphic class for cells : c : $\operatorname{Class}(\forall(X)$ PrivateCell $\{X\}) \triangleq$

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Polymorphic class for cells : c : Class $(\forall(X)$ PrivateCell $\{X\}) \triangleq$

```
[ new = \varsigma(z : Class(\forall(X)PrivateCell{X}))
    \lambda(X)([ contents = \varsigma(s: PrivateCell{X})z.contents(X)(s),
    get = \varsigma(s:PrivateCell{X})z.get(X)(s),
    set = \varsigma(s:PrivateCell{X})z.\operatorname{set}(X)(s)] ),
contents = \lambda(X)(\lambda(s:PrivateCell{X})s.contents),
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```

Finally c.new(Nat) : PrivateCell $\{N a t\}=[$ contents : Nat, get : Nat, set : $\mathrm{Nat} \rightarrow$ RomCell ] is a private cell that stores natural numbers as desired.

## Conclusion

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- The theory of objects is not recognized as having a foundational basis as of now
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- Yet, through the study of $\varsigma$-calculus, we saw that such foundations can be provided (at least, some foundation exists)
- Through the notion of "self" of this calculus, objects have acquired an expressive and robust typing system.
- Through subtyping alone, the four OOL principles of abstraction, encapsulation, inheritance, and polymorphism have been properly enforced.


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My intuition : investigation of the typing theory of processes, such as presented in $\pi$-calculus, may allow a representation of objects that is faithful with respect to subtyping and the notion of "self"; that would mean endowing objects with a natural form of concurrency.

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The firing of these localized functions resembles the firing of transitions in a Petri net; but in my model, the state of the system is not represented by tokens in a region, but by values that fall under certain types associated to regions...

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A circuit made of logic gates operating on boolean types would be a good example. The state of the system would be represented by values that circulate in the wires. I would model logic gates as methods that fire to affect the state of the system locally on the wires.

My belief is that, perhaps, encapsulation, abstraction and subtyping can be rendered through typing and localization in my model...

