



UNIVERSITY OF
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CPSC 531: System Modeling and Simulation

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“A person with one watch knows what time it is.
A person with two watches is never quite sure.”

-Segal's Law



- Purpose: estimate system performance from simulation output

- Understand:
 - Terminating and non-terminating simulations
 - Transient and steady-state behavior

- Learn about statistical data analysis:
 - Computing confidence intervals
 - Determining the number of observations required to achieve a desired confidence interval

- Measure of performance and error
- Transient and steady state
 - Types of simulations
 - Steady-state analysis
 - Initial data deletion
 - Length of simulation run
- Confidence interval
 - Estimating mean and variance
 - Confidence interval for small and large samples
 - Width of confidence interval

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- Output data are random variables, because the input variables are stochastic, and model is basically an input-output transformation

- **A queueing example: Banff park entry booth**
 - Arrival rate \sim Poisson arrival process (λ per minute)
 - Service time $\sim Exponential(\mu = 1.5)$ minutes
 - System performance: long-run average queue length
 - Question 1: does simulation model result agree with M/M/1 model?
 - Question 2: is queueing better/same/worse for HyperExp() service?
 - Question 3: how much better would it be with two servers?
 - Suppose we run the simulation 3 times, i.e., 3 **replications**
 - Each replication is for a total of 5,000 minutes
 - Divide each replication into 5 equal subintervals (i.e., batches) of 1000 minutes
 - $Y_{i,j}$: Average number of cars in queue from time $(j - 1) \times 1000$ to $j \times 1000$ in replication i
 - Y_i : Average number of cars in queue in replication i


■ queueing example (cont'd):

- Batched average queue length for 3 independent replications:

Batching Interval (minutes)	Batch, j	Replication		
		1, Y_{1j}	2, Y_{2j}	3, Y_{3j}
[0, 1000)	1	3.61	2.91	7.67
[1000, 2000)	2	3.21	9.00	19.53
[2000, 3000)	3	2.18	16.15	20.36
[3000, 4000)	4	6.92	24.53	8.11
[4000, 5000)	5	2.82	25.19	12.62
[0, 5000)		3.75	15.56	13.66

- Inherent variability in stochastic simulation both within a single replication and across different replications
- The average across 3 replications, i.e., Y_1, Y_2, Y_3 , can be regarded as **independent** observations, but averages within a replication, e.g., $Y_{11}, Y_{12}, Y_{13}, Y_{14}, Y_{15}$, are **not**.

- Consider estimating a performance parameter Θ
 - The true value of Θ is unknown
 - Can only observe simulation output
 - Estimate Θ using independent observations obtained from independent simulation runs (i.e., replications)

- $\hat{\Theta}$: estimation of Θ
 - Is unbiased if: $E[\hat{\Theta}] = \Theta$ 
 - Is biased if: $E[\hat{\Theta}] \neq \Theta$
 - Estimation bias = $E[\hat{\Theta}] - \Theta$

- Confidence Interval (CI):
 - We cannot know for certain how far $\hat{\Theta}$ is from Θ
 - CI attempts to bound the estimation error $|\Theta - \hat{\Theta}|$
 - The more replications we make, the lower the error in $\hat{\Theta}$

- Example: queueing system
 - Y : long-run average queue length
 - Y_i : average queue length in simulation run i
 - Define estimator $\hat{Y} = \bar{Y}$, i.e.,

$$\hat{Y} = \frac{1}{8} (Y_1 + \dots + Y_8) = 14.814$$

- Can calculate a 95% confidence interval for Y such that:

$$\mathbb{P}(|Y - \hat{Y}| \leq \epsilon) = 0.95$$

- For instance: $11.541 \leq Y \leq 18.087$

i	Y_i
1	15.028
2	13.385
3	18.891
4	10.559
5	8.866
6	15.883
7	18.598
8	17.302

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1. Terminating simulation:

there is a natural event that specifies the length of the simulation:

- Runs for some duration of time T_E , where E is a specified event that stops the simulation
 - Starts at time 0 under well-specified initial conditions
 - Ends at specified stopping time T_E
-
- Example: Simulating banking operations over “one day”
 - Opens at 8:30 am (time 0) with no customers present and 8 of the 11 tellers working (initial conditions), and closes at 4:30 pm (Time $T_E = 480$ minutes)

2. Non-terminating simulation:

No natural event specifying length of the simulation

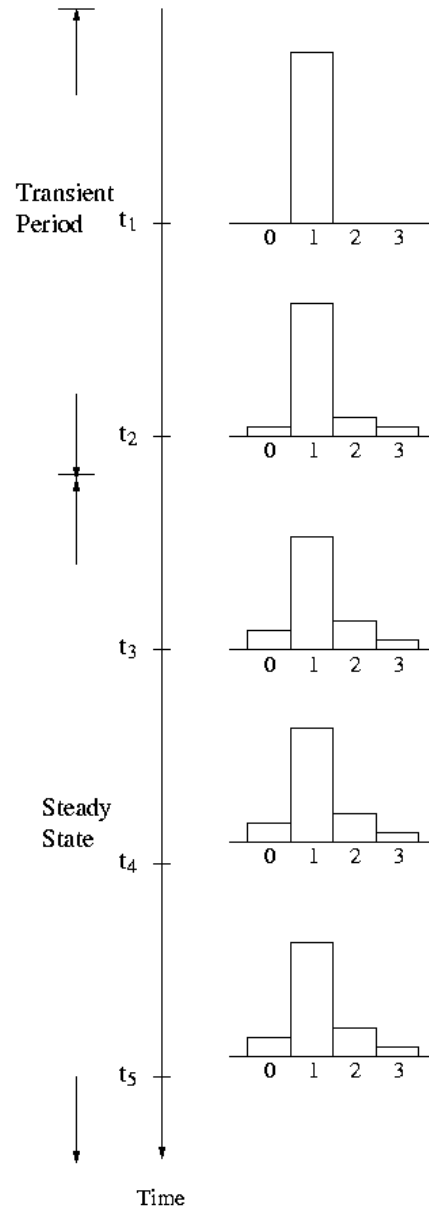
- Runs continuously, for a very long period of time
 - Initial conditions defined by the performance analyst
 - Runs for some **analyst-specified** period of time T_E
 - Of interest are *transient* and *steady state* behavior
- Example: Simulating banking operations to compute the “long-run” mean response time of customers

- Whether a simulation is considered to be terminating or non-terminating depends on both
 - The objectives of the simulation study, and
 - The nature of the system.
- Similar statistical techniques applied to both types of simulations to estimate performance and error
- For non-terminating simulations:
 - Transient and steady-state behavior are different
 - Generally, steady-state performance is of interest

Consider a queueing system

- Define $P(n, t) = \mathbb{P}(n \text{ in system at time } t)$
 - Depends on the initial conditions
 - Depends on time t
- Steady state behavior
 - System behavior over long-run: $P(n) = \lim_{t \rightarrow \infty} P(n, t)$
 - Independent of the initial conditions
 - Independent of time

Transient and Steady-State Behavior



- General approach based on independent replications:
 - Choose the initial conditions
 - Determine the length of simulation run
 - Run the simulation and collect data

- **Problem:** steady-state results are affected by using artificial and potentially unrealistic initial conditions

- **Solutions:**
 1. Intelligent initialization
 2. Simulation warmup (initial data deletion)

- Initialize the simulation in a state that is more representative of long-run conditions
- If the system exists, collect data on it and use these data to specify typical initial conditions
- If the system can be simplified enough to make it mathematically solvable (e.g. queueing models), then solve the simplified model to find long-run expected or most likely conditions, and use that to initialize the simulation

- Divide each simulation into two phases:
 - Initialization phase, from time 0 to time T_0
 - Data-collection phase, from T_0 to stopping time $T_0 + T_E$
- Important to do a thorough job of investigating the initial-condition bias:
 - Bias is not affected by the number of replications, rather, it is affected only by deleting more data (i.e., increasing T_0) or extending the length of each run (i.e. increasing T_E)
- How to determine T_0 and T_E ?

■ How to determine T_0 ?

- After T_0 , system should be more nearly representative of steady-state behavior
- System has reached steady state: the probability distribution of the system state is close to the steady-state probability distribution
- No widely accepted, objective and proven technique to guide how much data to delete to reduce initialization bias to a negligible level
- Heuristics such as plotting the moving averages can be used

- **How to implement data deletion in DES?**
 - At initialization, schedule a `reset` event at `clock + T0`
 - `reset` event routine: reset all statistical counters (for data collection) to their initial values
 - At the end of simulation, statistical counters contain data collected after the transient period

- How to determine T_E ?
 - Too short: results may not be reliable
 - Too long: wasteful of resources
- Method to determine length of run
 - Perform independent replications
 - For each replication, perform initial data deletion
 - Select length of run and number of replications such that the confidence intervals for the performance measures of interest narrow to the desired widths

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Terminology

- **Observation:** a single value of a performance measure from an experiment
Example: mean response time of a web server
- **Sample:** the set of observations of a performance measure from an experiment

- Generate several million random numbers with a given distribution and draw a sample of m observations
- Sample mean \neq population mean
- In discrete-event simulation, population characteristics such as mean and variance are unknown
 - Need to estimate them using simulation output

- Consider a sample of m observations, denoted by Y_1, Y_2, \dots, Y_m
- Example: Y_i is the mean response time of a web server in the i -th experiment
- **Sample mean:**

$$\bar{Y} = \frac{1}{m} \sum_{i=1}^m Y_i$$

- Sample mean \bar{Y} is an unbiased estimator for the unknown population mean

- **Sample variance:**

$$s^2 = \frac{1}{m - 1} \sum_{i=1}^m (Y_i - \bar{Y})^2$$

- s^2 is an unbiased estimator for the unknown population variance
- The divisor for s^2 is $m - 1$ and not m
 - This is because only $m - 1$ of the m differences are independent
 - Given $m - 1$ differences, m -th difference can be computed since the sum of all m differences must be zero
 - The number of independent terms in a sum is also called its *degrees of freedom*

Consider a simulation study

- Y : random variable denoting the performance measure corresponding to the simulation output
 - Example: average wait time of customers in a bank

- **Problem:** Y varies across different simulation runs
 - Consider m simulation runs
 - Y_i : simulation output in simulation run i
 - Generally, $Y_1 \neq Y_2 \neq \dots \neq Y_m$

- **Solutions:**
 1. Characterize distribution of Y (e.g., CDF)
 2. Characterize statistics of Y (e.g., mean and variance)

Consider a simulation study

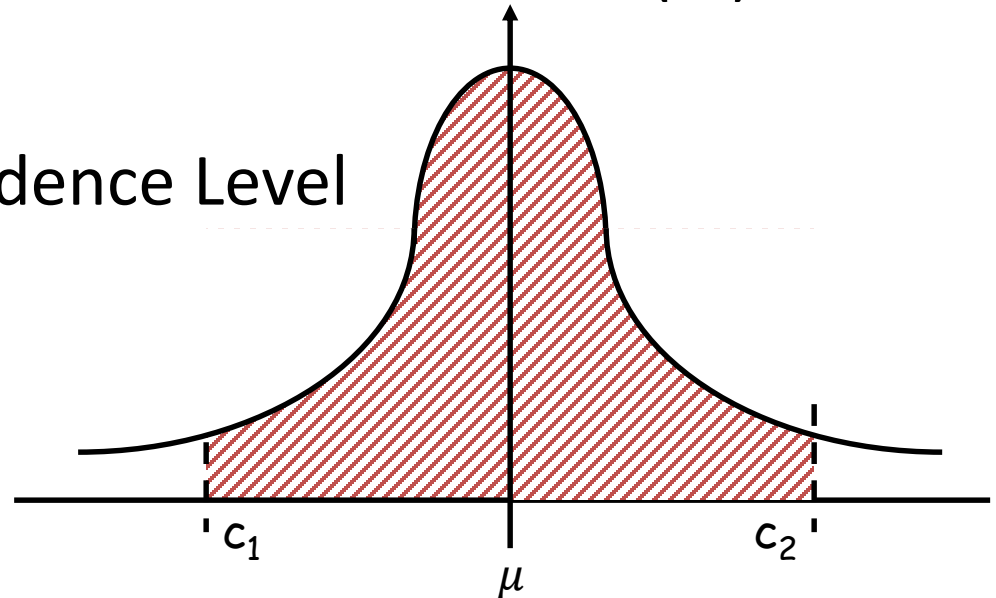
- Y : random variable denoting the performance measure corresponding to the simulation output
 - Example: average wait time of customers in a bank
- Objective is to characterize the unknown mean $\mu = E[Y]$
 - **Algorithm:**
 - Make m independent simulation runs to obtain m observations Y_1, Y_2, \dots, Y_m
 - Sample mean \bar{Y} is an unbiased estimator for μ
 - **Question:** How far is \bar{Y} from μ ?
 - Determine confidence interval for mean

- Determine bounds c_1 and c_2 such that:

$$\mathbb{P}(c_1 \leq \mu \leq c_2) = 1 - \alpha$$

- $[c_1, c_2]$: $(1 - \alpha)100\%$ Confidence Interval (CI)

- $(1 - \alpha)100\%$: Confidence Level



- \bar{Y} is a random variable:

$$\bar{Y} = \frac{Y_1 + Y_2 + \cdots + Y_m}{m}$$

where the Y_i 's are IID with the same distribution as $Y \sim N(\mu, \sigma^2)$

- We have:

$$E[\bar{Y}] = \frac{E[Y_1] + \cdots + E[Y_m]}{m} = \frac{m \mu}{m} = \mu$$
$$V[\bar{Y}] = \frac{V[Y_1] + \cdots + V[Y_m]}{m^2} = \frac{m \sigma^2}{m^2} = \frac{\sigma^2}{m}$$

- μ and σ^2 unknown but can be estimated by \bar{Y} and s^2

- Define the normalized random variable X as

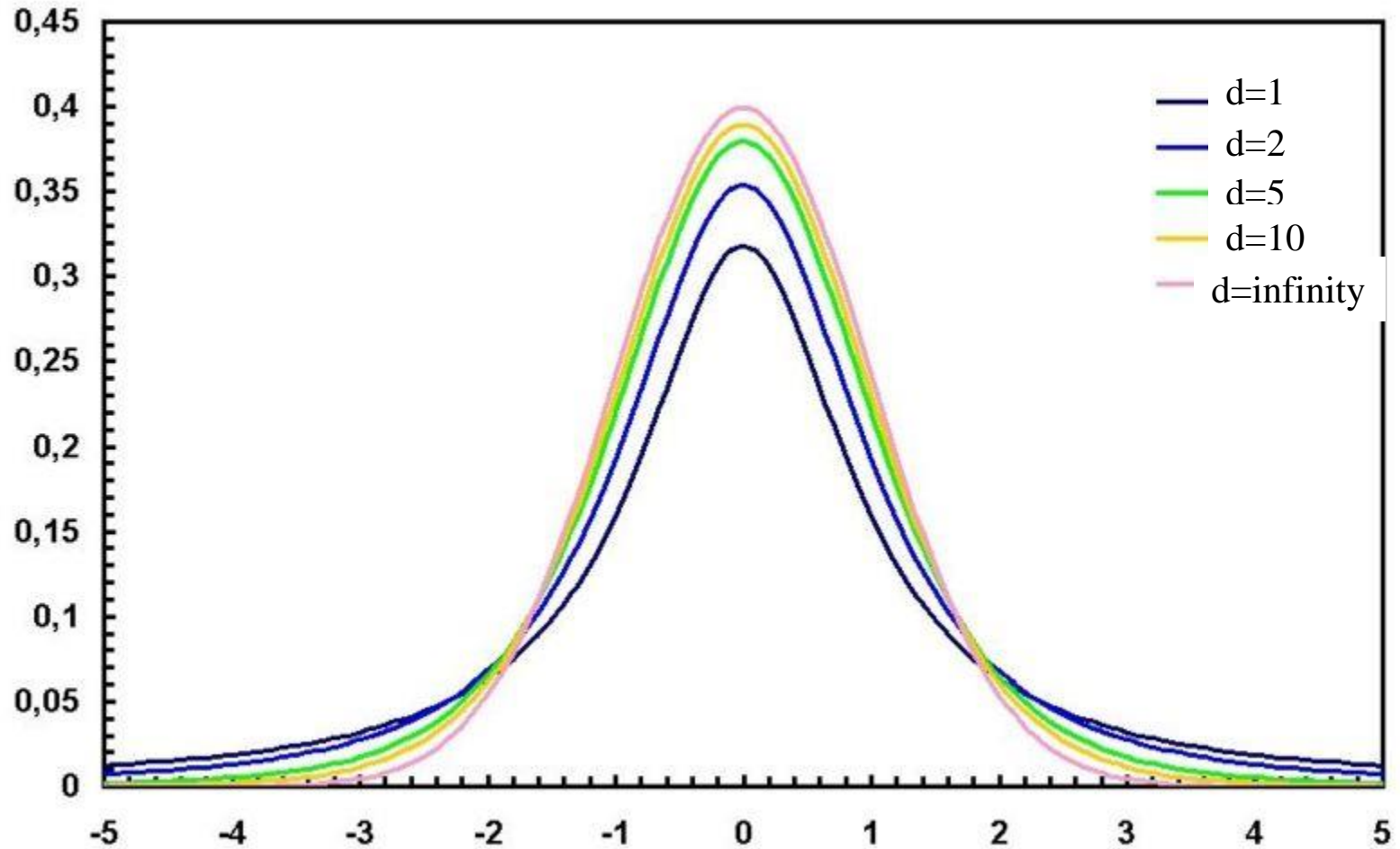
$$X = \frac{\bar{Y} - \mu}{s/\sqrt{m}}$$

- **Theorem:** The distribution of X is independent of unobservable parameter μ
 - For large m : X follows a standard normal distribution
 - For small m : X follows a Student's t -distribution

- Define the normalized random variable T as

$$T = \frac{\bar{Y} - \mu}{s/\sqrt{m}}$$

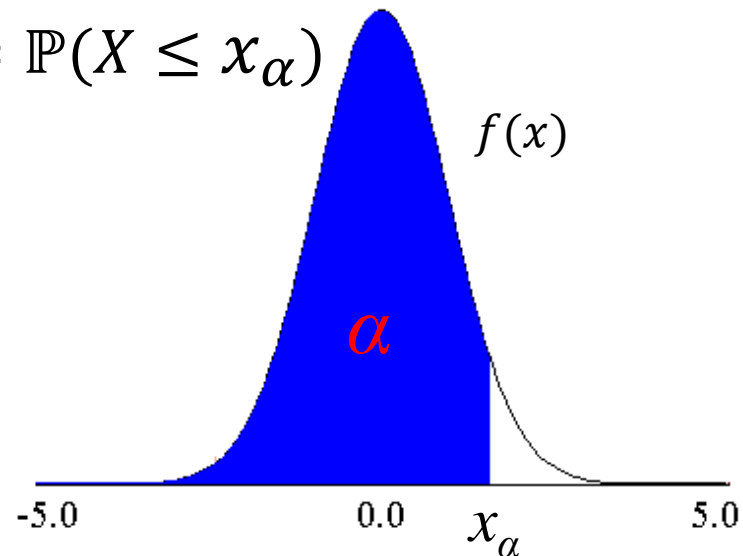
- T has a standard **Student's t -distribution** with $d = m - 1$ degrees of freedom
 - It describes the distribution of the mean of a sample of m observations
 - Symmetric distribution
 - $E[T] = 0$, and $V[T] = \frac{d}{d-2}$ for $d \geq 2$
 - As $m \rightarrow \infty$, we have $T \sim N(0, 1)$



Probability Density Function (PDF)

- **Quantile:** The x value at which the CDF takes a value α is called the α -quantile or 100α -percentile. It is denoted by x_α :

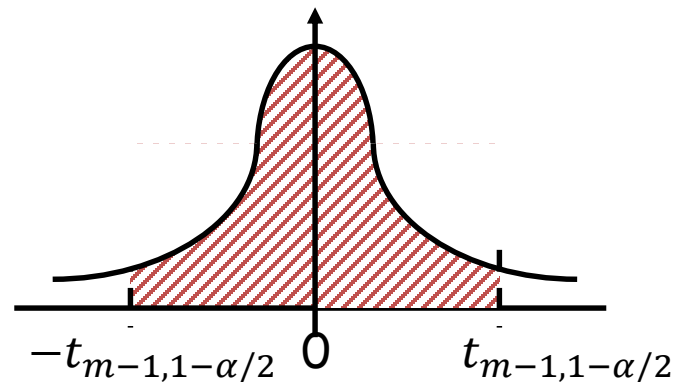
$$\alpha = F(x_\alpha) = \mathbb{P}(X \leq x_\alpha)$$



- Example: X has standard normal distribution
 - 95-percentile = 0.95-quantile = 1.6449
 - 25-percentile = 0.25-quantile = - 0.6745

- Define $c = t_{m-1, 1-\alpha/2}$ as:
($1 - \alpha/2$)-quantile of T with $d = m - 1$ degrees of freedom:

$$\mathbb{P}(T \leq t_{m-1, 1-\alpha/2}) = 1 - \alpha/2$$



- Note that $t_{m-1, 1-\alpha/2}$ does not depend on the value of the unobservable population mean μ

- Therefore

$$\mathbb{P}(-c \leq T \leq c) = 1 - \alpha$$

- Which means

$$\mathbb{P}\left(-c \leq \frac{\bar{Y} - \mu}{s/\sqrt{m}} \leq c\right) = 1 - \alpha$$

$$\Rightarrow \mathbb{P}\left(\bar{Y} - c \frac{s}{\sqrt{m}} \leq \mu \leq \bar{Y} + c \frac{s}{\sqrt{m}}\right) = 1 - \alpha$$

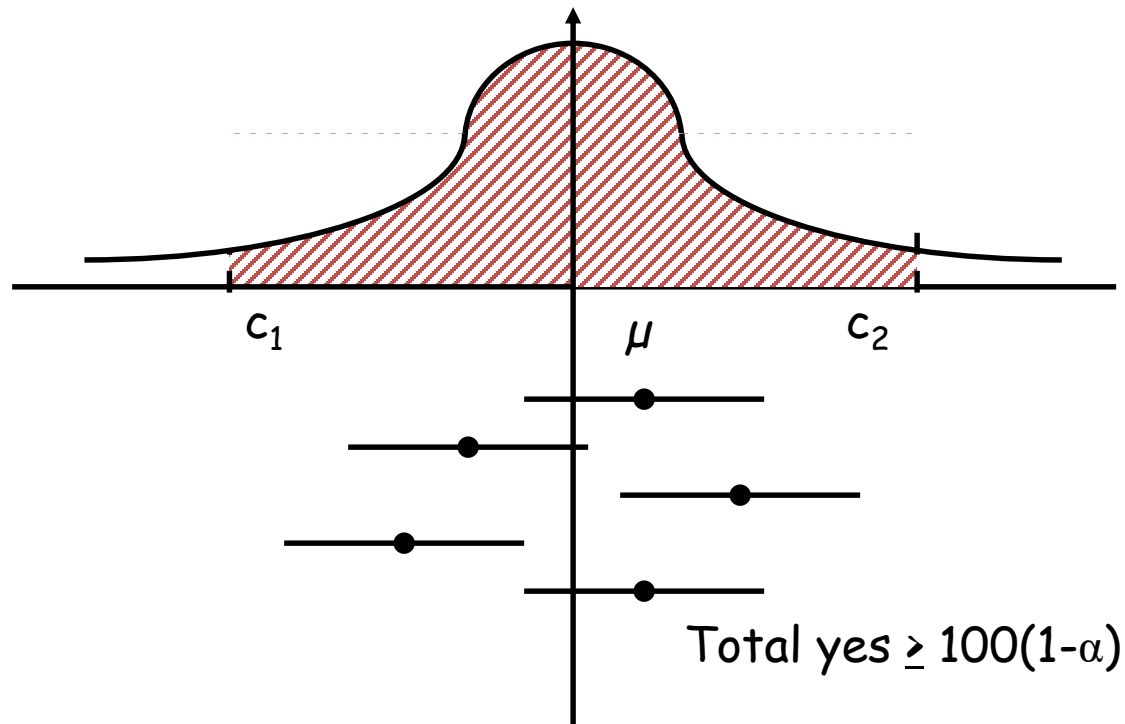
- $(1-\alpha)100\%$ confidence interval of μ is given by

$$\left[\bar{Y} - c \frac{s}{\sqrt{m}}, \quad \bar{Y} + c \frac{s}{\sqrt{m}} \right]$$

- Sample:
-0.04, -0.19, 0.14, -0.09, -0.14, 0.19, 0.04, and 0.09
- Mean = 0, Sample standard deviation = 0.138
- For 90% confidence interval: $t_{7, 0.95} = 1.895$
- Confidence interval for the mean

$$0 \mp 1.895 \times \frac{0.138}{\sqrt{8}} = 0 \mp 0.093 = (-0.093, 0.093)$$

- If we take 100 samples and construct confidence interval for each sample, the interval would include the population mean in 90 cases.



- 10 replications of Banff park entry gate simulation
- Warmup: 10,000 minutes
- Number of cars: 60,000

λ	$1/\mu$	ρ	Mean Q	Std Dev
0.5	1.5	0.75	3.019	0.109
0.55	1.5	0.825	4.715	0.174
0.60	1.5	0.90	9.042	0.980
0.65	1.5	0.975	39.876	12.76

- See graph online for 90% confidence intervals

- 10 batches from Banff park entry gate simulation
- Warmup: 0 minutes
- Number of cars: 500,000

λ	$1/\mu$	ρ	Mean Q	Std Dev
0.5	1.5	0.75	2.997	0.088
0.55	1.5	0.825	4.813	0.206
0.60	1.5	0.90	9.033	0.608
0.65	1.5	0.975	42.22	14.72

- Define normalized random variable Z as

$$Z = \frac{\bar{Y} - \mu}{s/\sqrt{m}}$$

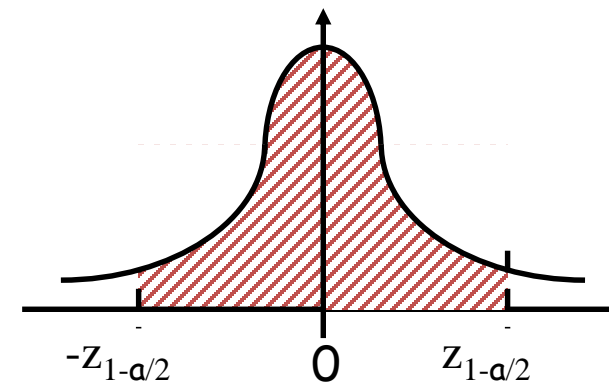
where s is the sample standard deviation

- From **Central Limit Theorem**: Z has standard normal distribution for large m

- $(1-\alpha)100\%$ confidence interval for μ :

$z_{1-\alpha/2} = (1-\alpha/2)$ -quantile of $N(0,1)$

$$\left[\bar{Y} - z_{1-\alpha/2} \frac{s}{\sqrt{m}}, \bar{Y} + z_{1-\alpha/2} \frac{s}{\sqrt{m}} \right]$$



- $\bar{Y} = 3.90$, $s = 0.95$, and $m = 32$
- A 90% confidence interval for the mean
 $= 3.90 \mp (1.645)(0.95)/\sqrt{32} = (3.62, 4.17)$

- We can state with 90% confidence that the population mean is between 3.62 and 4.17

A 95% confidence interval for the mean $= 3.90 \mp (1.960)(0.95)/\sqrt{32}$
 $= (3.57, 4.23)$

A 99% confidence interval for the mean $= 3.90 \mp (2.576)(0.95)/\sqrt{32}$
 $= (3.46, 4.33)$

- Width of the confidence interval is

$$2 \cdot t_{m-1, 1-\frac{\alpha}{2}} \cdot \frac{s}{\sqrt{m}}$$

- Width can be reduced by
 - Using a larger m (i.e., more simulation runs)
 - Using a smaller s (i.e., longer simulation runs)

- Suppose the desired width of the confidence interval is δ , and m replications have been made but the desired width is not met:
 - Total number of replications required can be estimated by

$$m^* = \left(2 \cdot t_{m-1, 1-\frac{\alpha}{2}} \cdot \frac{s}{\delta} \right)^2$$

- Number of additional replications required = $m^* - m$

- An alternative to increasing m is to increase total run length $T_0 + T_E$ for each replication

- Approach: for $\beta \geq 1$
 - Increase run length from $(T_0 + T_E)$ to $\beta(T_0 + T_E)$, and
 - Delete additional amount of data, from time 0 to time βT_0

