



An Energy Efficient Hierarchical Clustering Algorithm for Wireless Sensor Networks

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Prepared by

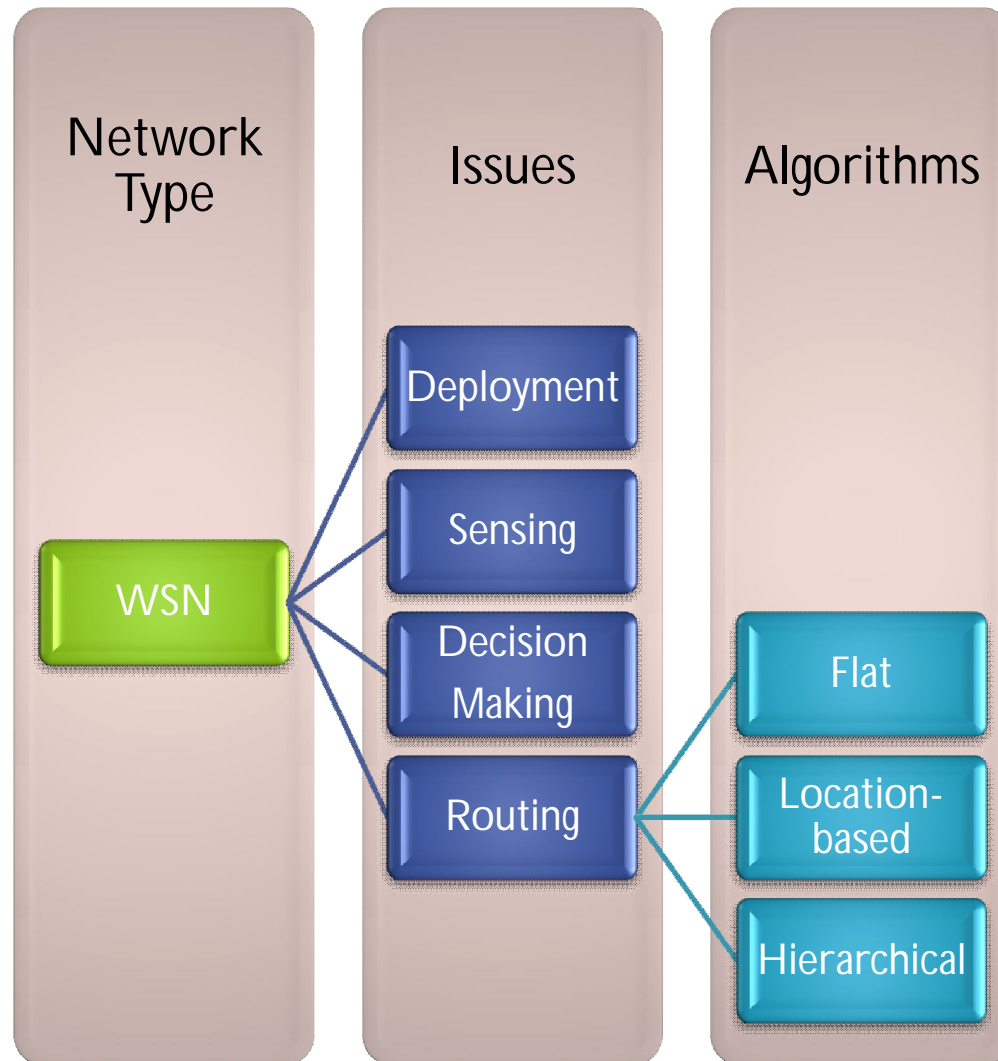
Mohamed Elersy

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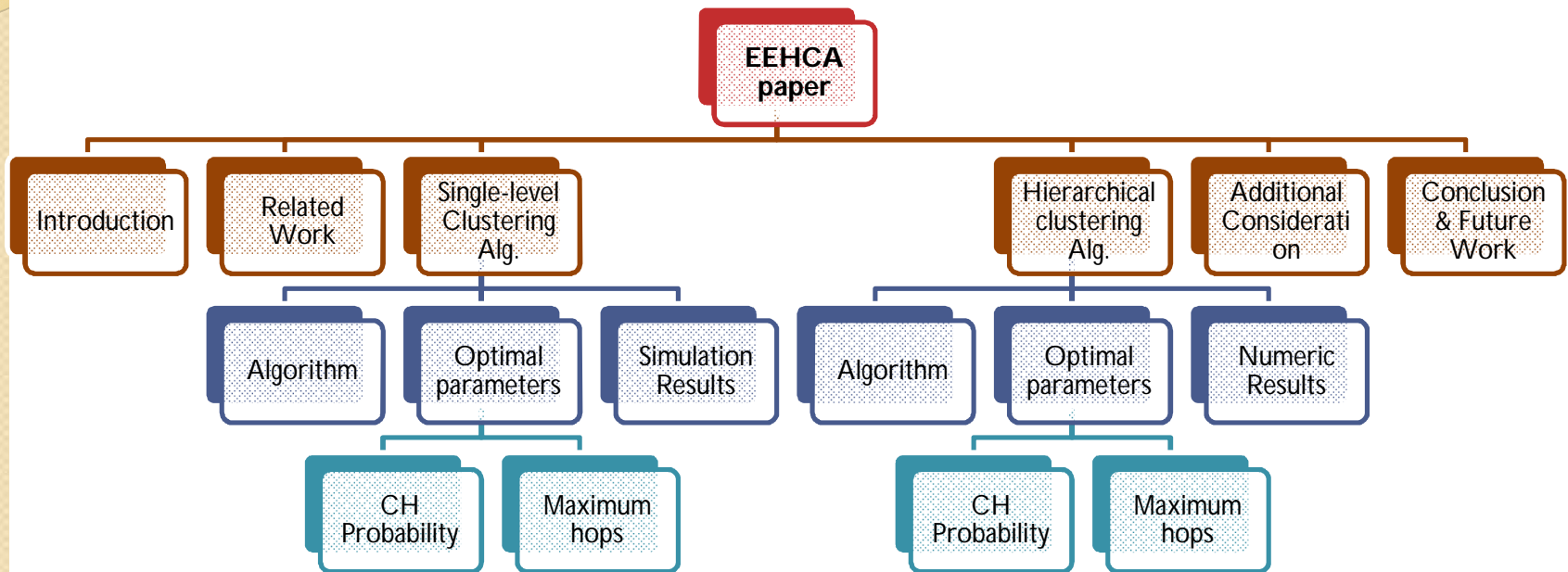
About the paper

- Appeared in INFOCOM 2003
- 11 pages
- 30 references
- Cited by 673 papers

Topic classification



Paper Structure





Related Work

- LCA
- LCA2
- WCA
- DCA
- DMAC
- LEACH
- non-purely hierarchical models

Assumptions (1/2)

- a) The sensors are distributed as per a homogeneous spatial Poisson process of intensity λ in 2-D space.
- b) All sensors transmit at the same power level so have the same radio range.
- c) Data exchanged between two communicating sensors not within each others' radio range is forwarded by other sensors.

Assumptions (2/2)

- d) A distance of d between any sensor and its cluster head is equivalent to d / r hops.
- e) Each sensor uses one unit of energy to transmit or receive one unit of data.
- f) A routing infrastructure is in place; so, only the sensors on the routing path forward the data.
- g) The communication environment is contention- and error-free. (No retransmit)

Single-level Clustering Algorithm

1. Each sensor becomes a cluster-head (CH) with probability p and advertises itself as a CH to the sensors within its radio range.
2. The advertisement is forwarded to all the sensors that are no more than k hops away from CH. Any sensor that receives such advertisements and is not itself a CH joins the cluster of the closest CH.
3. Any sensor that is neither a CH nor has joined any cluster itself becomes a CH.

Optimal parameters

Probability of becoming a Clusterhead

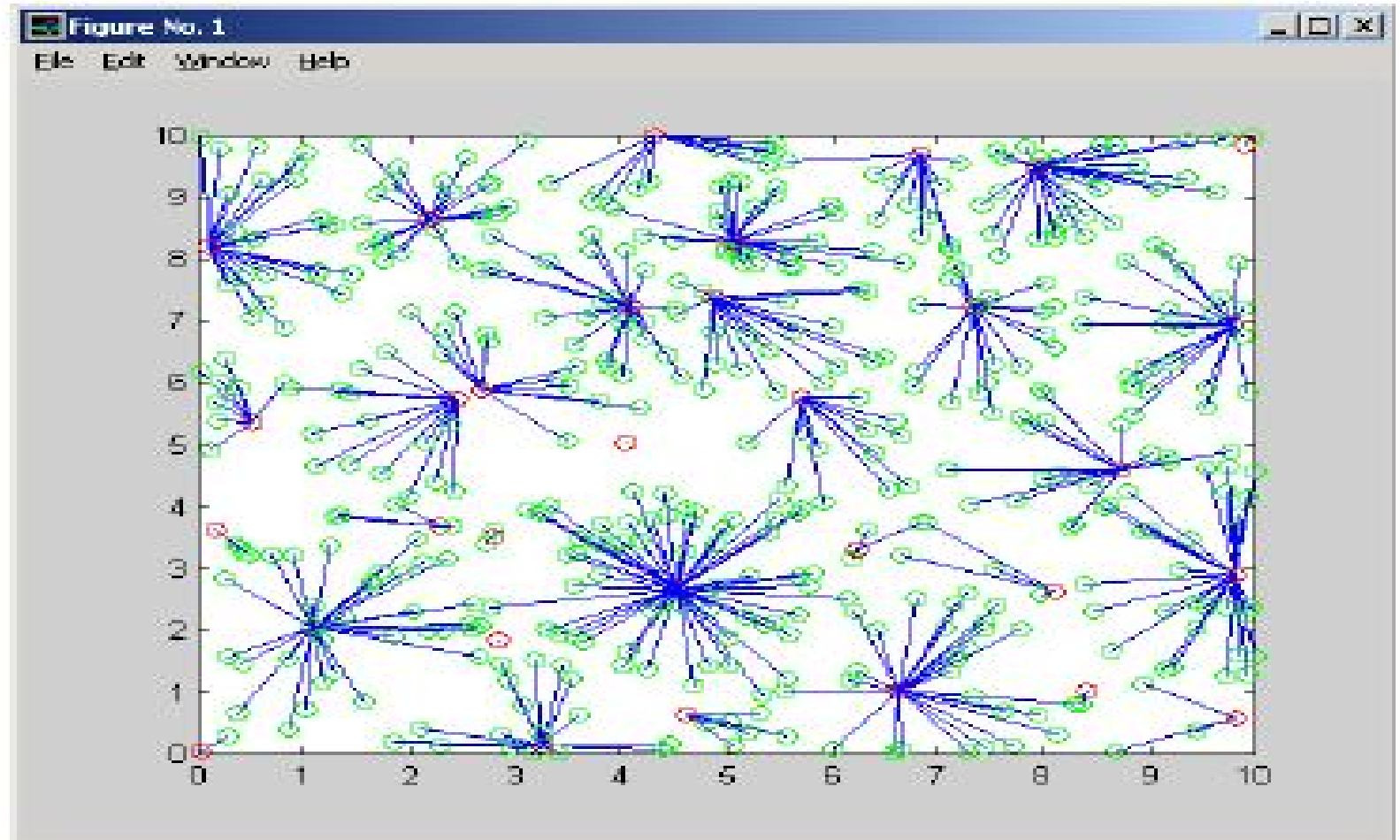
$$p = \left[\frac{1}{3c} + \frac{\sqrt[3]{2}}{3c(2 + 27c^2 + 3\sqrt{3c}\sqrt{27c^2 + 4})^{1/3}} + \frac{(2 + 27c^2 + 3\sqrt{3c}\sqrt{27c^2 + 4})^{1/3}}{3c} \cdot \frac{1}{\sqrt[3]{2}} \right]^2$$

where $c = 3.06a\sqrt{\lambda}$.

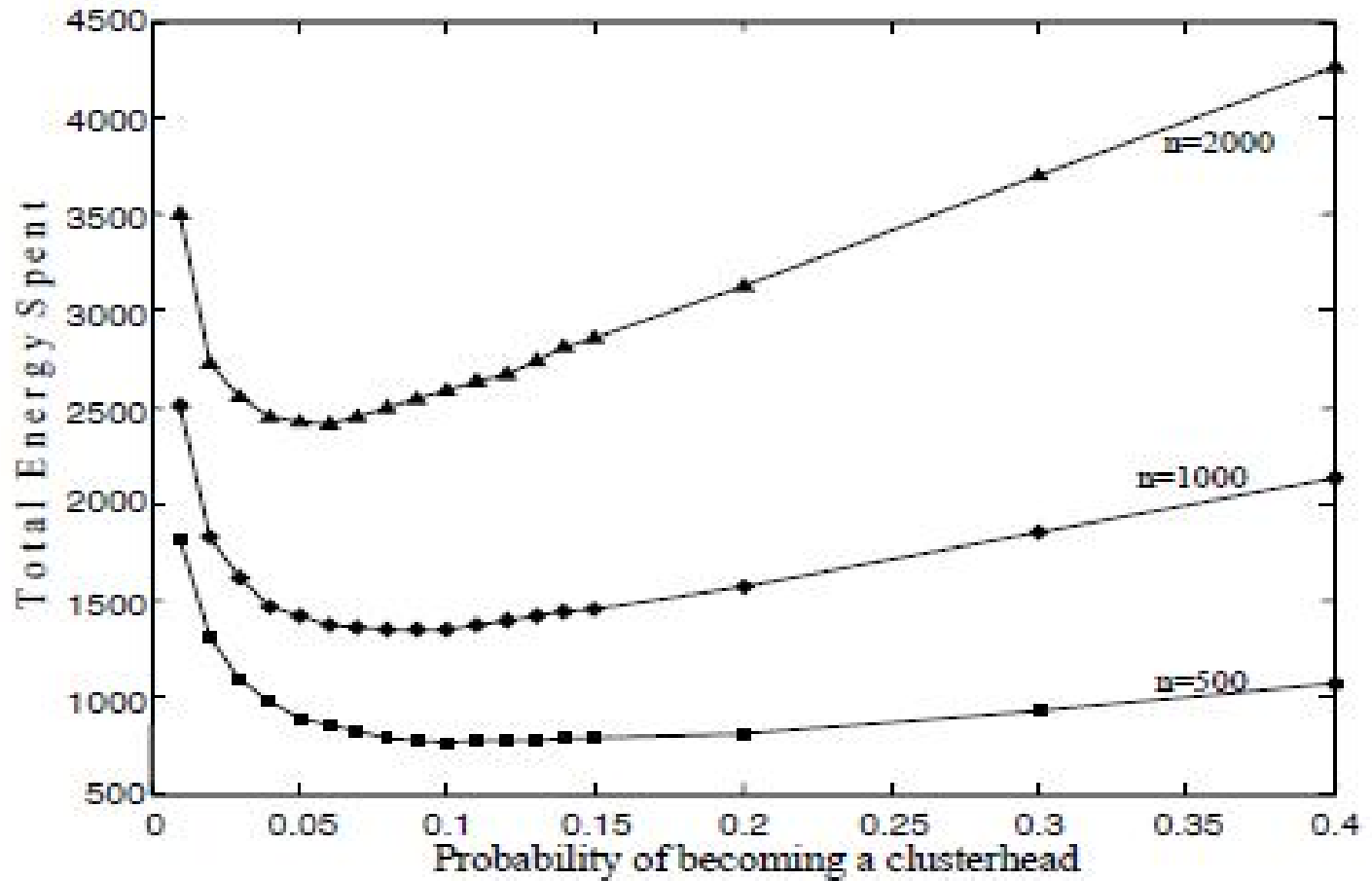
Maximum number of hops allowed from a sensor to its clusterhead

$$k_1 = \left\lceil \frac{1}{r} \sqrt{\frac{-0.917 \ln(\alpha/7)}{p_1 \lambda}} \right\rceil.$$

Results (1/4)



Results (2/4)

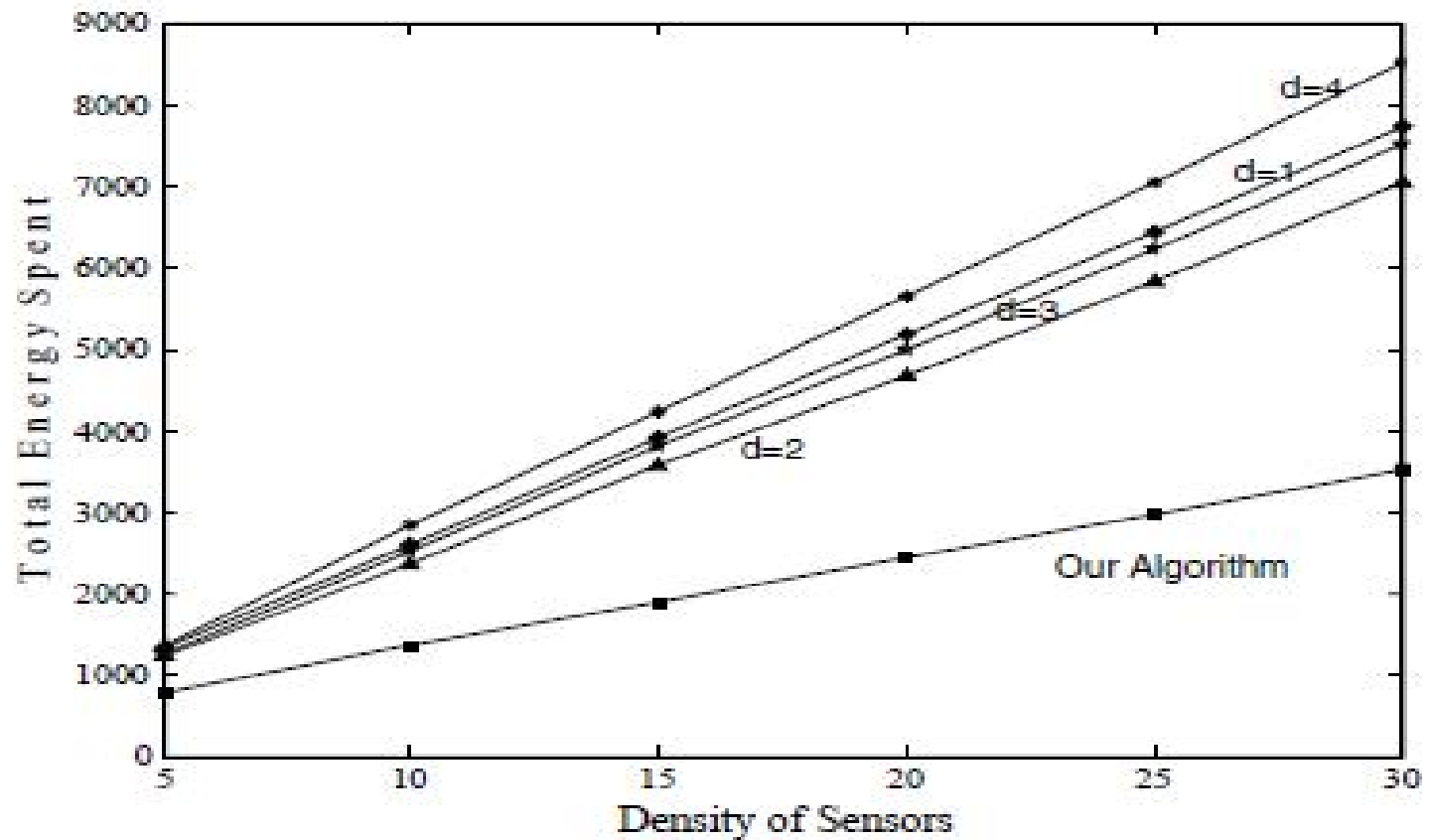


Results (3/4)

TABLE I ENERGY MINIMIZING PARAMETERS FOR THE ALGORITHM

Number of Sensors (n)	Density (d)	Probability (P_{opt})	Maximum Number of Hops (k)
500	5	0.1012	5
1000	10	0.0792	4
1500	15	0.0688	3
2000	20	0.0622	3
2500	25	0.0576	3
3000	30	0.0541	3

Results (4/4)



Hierarchical Clustering Alg. (1/2)

- Each sensor decides to become a level-1 CH with p_1 and advertises itself as a CH to the sensors within its radio range.
- This advertisement is forwarded to all the sensors within k_1 hops of the advertising. Each sensor that receives an advertisement joins the cluster of the closest level-1 CH; the remaining sensors become forced level-1 CHs.

Hierarchical Clustering Alg. (2/2)

- Level-1 CHs then elect themselves as level-2 CHs with a certain probability p_2 and broadcast their decision of becoming a level-2 CH. This decision is forwarded to all the sensors within k_2 hops.
- The level-1 CHs that receive the advertisements from level-2 CHs joins the cluster of the closest level-2 CH. All other level-1 CHs become forced level-2 CHs.
- CH at level $3, 4, \dots, h$ are chosen in similar fashion, with probabilities p_3, p_4, \dots, p_h respectively

Optimal parameters

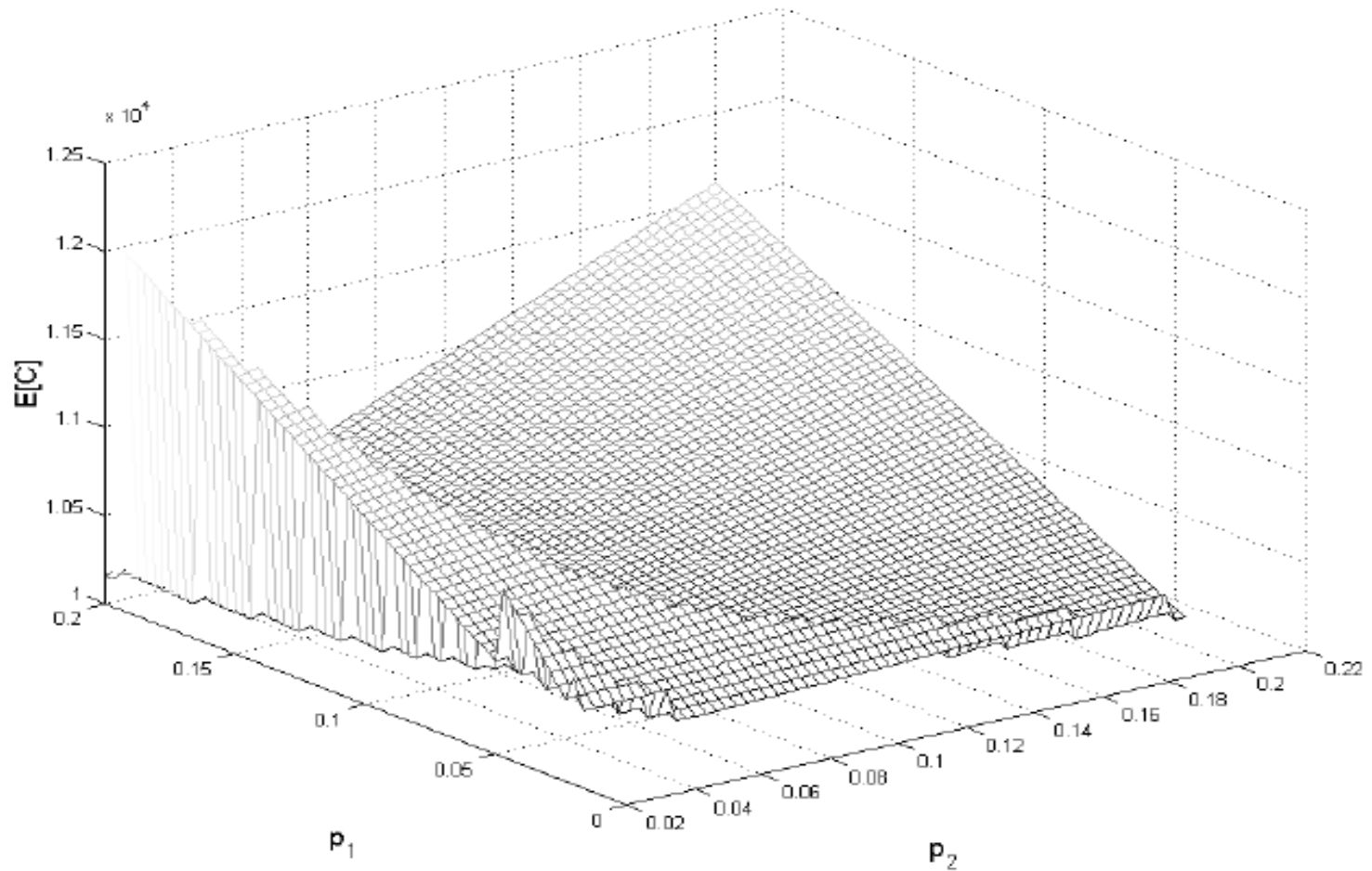
Probability of becoming a Clusterhead

$$\begin{aligned} E[C] &= E[E[C \mid N = n]] \\ &= \lambda A \prod_{i=1}^h p_i \left[\frac{0.765\alpha}{r} \right] \\ &\quad + \lambda A \sum_{i=1}^h (1 - p_i) \prod_{j=1}^{i-1} (p_j) \left[\frac{1}{2r \sqrt{\lambda \prod_{j=1}^i p_j}} \right]. \end{aligned}$$

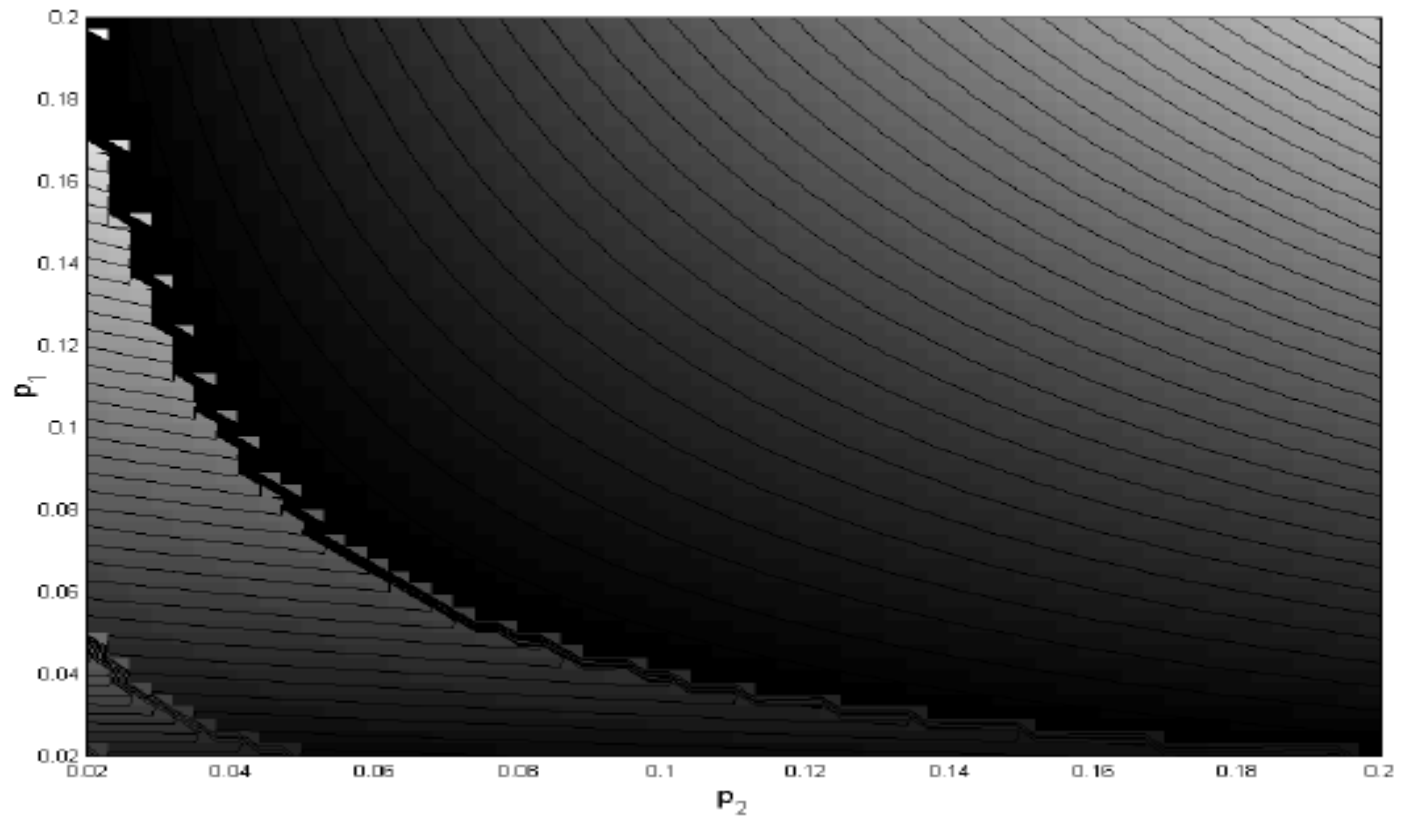
Maximum number of hops allowed from a sensor to its clusterhead

$$k_i = \left\lceil \frac{1}{r} \sqrt{\frac{-0.917 \ln(\alpha/7)}{\lambda \prod_{j=1}^i p_j}} \right\rceil.$$

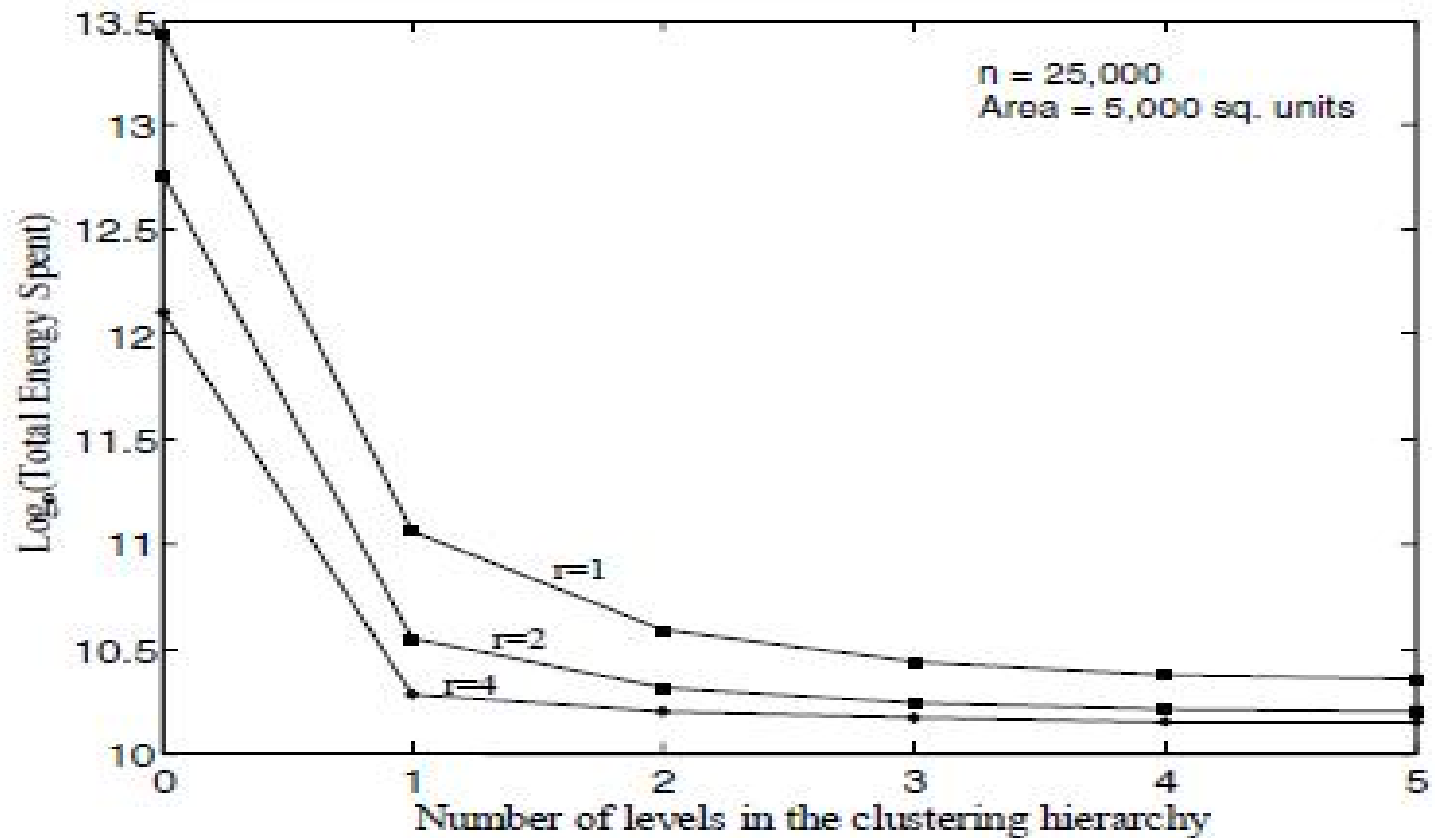
Results (1/4)



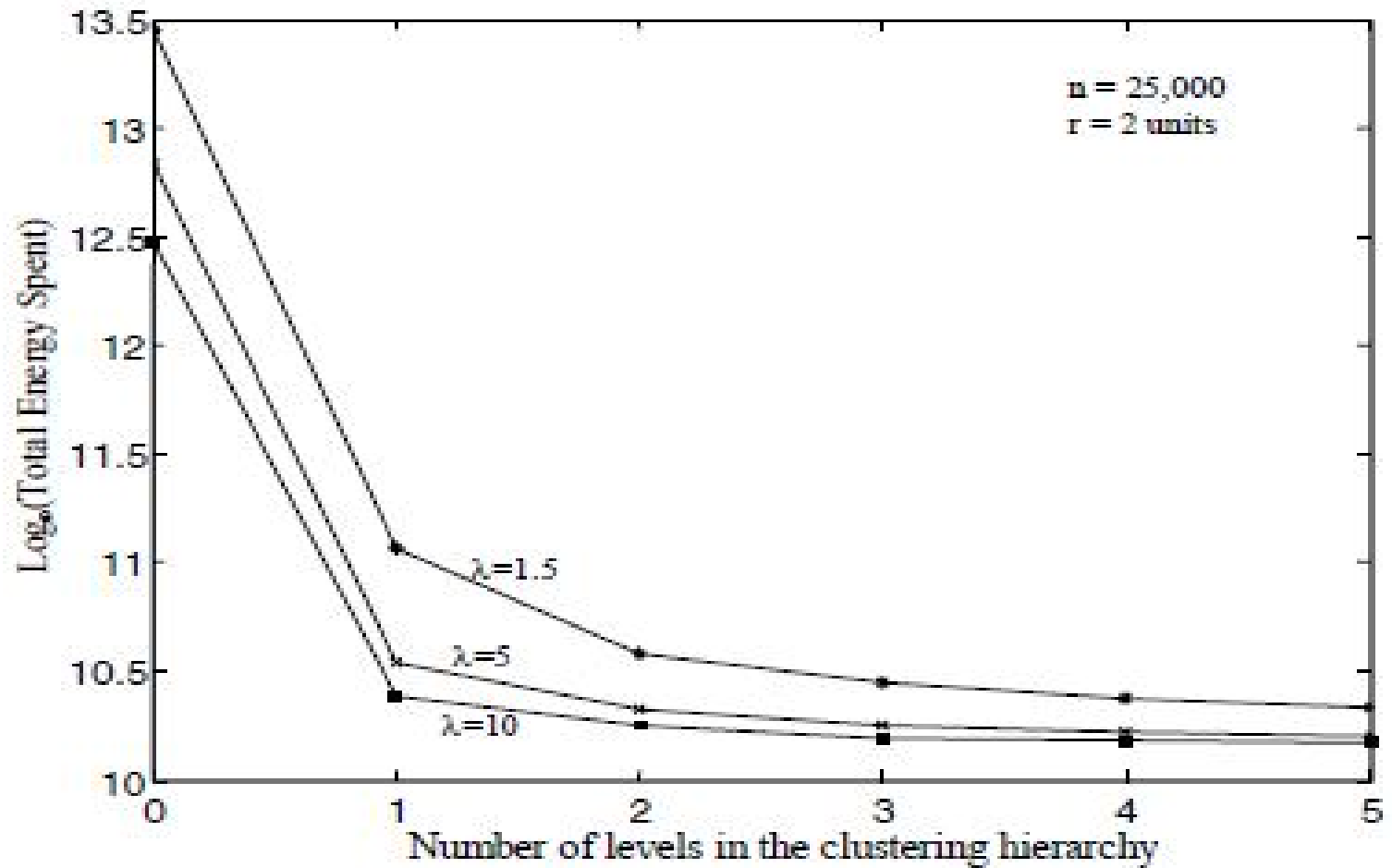
Results (2/4)



Results (3/4)



Results (4/4)



Q&A



Conclusion (1/2)

- A distributed algorithm proposed for organizing sensors into a hierarchy of clusters.
- Objective is minimizing the total energy spent in the system to communicate the information gathered by these sensors to the information-processing center.
- The optimal parameter values found for these algorithms that minimize the energy spent in the network.

Conclusion (2/2)

- Assumed that the communication environment is contention and error free.
- In a contention-free environment, the algorithm has a time complexity of $O(k_1 + k_2 + \dots + k_h)$, a significant improvement over the many $O(n)$ clustering algorithms in the literature.
- The algorithm is suitable for networks of large number of nodes.



Future Work

- Consider an underlying medium access protocol and investigate how that would affect the optimal probabilities of becoming a CH and the run-time of the algorithm.

Thank You

