

Comonadic notions of computation

Tarmo Uustalu¹ Varmo Vene²

¹Institute of Cybernetics, Tallinn

²University of Tartu

FMCS 2006, Kananaskis, 8 June 2006

Motivation

- Moggi and Wadler showed that effectful computations can be structured with monads.
- An effect-producing function from A to B is a map $A \rightarrow B$ in the Kleisli category, i.e., a map $A \rightarrow TB$ in the base category.
- Some examples applied in semantics:

$TA = A + 1$	partiality
$TA = A + E$	exceptions
$TA = A^E$	environment
$TA = A^* = \mu X. 1 + A \times X$	non-determinism
$TA = (A \times S)^S$	state

- Are all impure features captured by monads?
- What about comonads?

Comonads

Definition

A **comonad** on category \mathcal{C} is given by

- a functor $D : \mathcal{C} \rightarrow \mathcal{C}$
- a natural transformation $\varepsilon_A : DA \rightarrow A$
 - **counit** of the comonad
- a natural transformation $\delta_A : DA \rightarrow D^2A$
 - **comultiplication** of the comonad

s.t. following diagrams commute

$$\begin{array}{ccccc} & & DA & & \\ & \delta_A \swarrow & \parallel & \searrow \delta_A & \\ D^2A & \xrightarrow{D\varepsilon_A} & DA & \xleftarrow{\varepsilon_{DA}} & D^2A \end{array}$$

$$\begin{array}{ccc} DA & \xrightarrow{\delta_A} & D^2A \\ \delta_A \downarrow & & \downarrow D\delta_A \\ D^2A & \xrightarrow{\delta_{DA}} & D^3A \end{array}$$

Comonads

Comonads model notions of value in a context;

- DA is the type of contextually situated values of A .

A context-relying function from A to B

is a map $A \rightarrow B$ in the coKleisli category,

- i.e., a map $DA \rightarrow B$ in the base category.

Product (environment) comonad

- Functor: $DA = A \times E$

- Counit:

$$\begin{aligned} \varepsilon_A &: A \times E \rightarrow A \\ (a, e) &\mapsto a \end{aligned}$$

- Comultiplication:

$$\begin{aligned} \delta_A &: A \times E \rightarrow (A \times E) \times E \\ (a, e) &\mapsto ((a, e), e) \end{aligned}$$

Comonads

Streams comonad

• Functor: $DA = A^{\mathbb{N}} = \nu X.A \times X$

• Counit:

$$\begin{aligned}\varepsilon_A &: A^{\mathbb{N}} \rightarrow A \\ \alpha &\mapsto \alpha(0)\end{aligned}$$

• Comultiplication:

$$\begin{aligned}\delta_A &: A^{\mathbb{N}} \rightarrow (A^{\mathbb{N}})^{\mathbb{N}} \\ \alpha &\mapsto \lambda n.(\lambda m.\alpha(n+m)) \\ [a_0, a_1, a_2, \dots] &\mapsto [[a_0, a_1, a_2, \dots], [a_1, a_2, a_3 \dots], \dots]\end{aligned}$$

Comonads for stream functions

Dataflow computation = discrete-time signal transformations = stream functions.

Example: simple dataflow programs

$$\begin{aligned} \mathit{pos} &= 0 \text{ fby } (\mathit{pos} + 1) \\ \mathit{sum } x &= x + (0 \text{ fby } (\mathit{sum } x)) \\ \mathit{fact} &= 1 \text{ fby } (\mathit{fact} * (\mathit{pos} + 1)) \\ \mathit{fibo} &= 0 \text{ fby } (\mathit{fibo} + (1 \text{ fby } \mathit{fibo})) \end{aligned}$$

<i>pos</i>	0	1	2	3	4	5	6	...
<i>sum pos</i>	0	1	3	6	10	15	21	...
<i>fact</i>	1	1	2	6	24	120	720	...
<i>fibo</i>	0	1	1	2	3	5	8	...

Stream functions $A^{\mathbb{N}} \rightarrow B^{\mathbb{N}}$ are naturally isomorphic to $A^{\mathbb{N}} \times \mathbb{N} \rightarrow B$

Comonads for stream functions

General stream functions

- Functor: $DA = A^{\mathbb{N}} \times \mathbb{N}$

- Input streams with past/present/future:

$$a_0, a_1, \dots, a_{n-1}, \boxed{a_n}, a_{n+1}, a_{n+2}, \dots$$

- Counit:

$$\begin{aligned} \varepsilon_A &: A^{\mathbb{N}} \times \mathbb{N} \rightarrow A \\ (\alpha, n) &\mapsto \alpha(n) \end{aligned}$$

- Comultiplication:

$$\begin{aligned} \delta_A &: A^{\mathbb{N}} \times \mathbb{N} \rightarrow (A^{\mathbb{N}} \times \mathbb{N})^{\mathbb{N}} \times \mathbb{N} \\ (\alpha, n) &\mapsto (\lambda m. (\alpha, m), n) \end{aligned}$$

Comonads for stream functions

Causal stream functions

- Functor: $DA = A^+ \quad (\cong A^* \times A)$
- Input streams with past and present but no future
- Counit:

$$\begin{aligned} \varepsilon_A &: A^+ \rightarrow A \\ [a_0, \dots, a_n] &\mapsto a_n \end{aligned}$$

- Comultiplication:

$$\begin{aligned} \delta_A &: A^+ \rightarrow (A^+)^+ \\ [a_0, \dots, a_n] &\mapsto [[a_0], [a_0, a_1], \dots, [a_0, \dots, a_n]] \end{aligned}$$

Anticausal stream functions

- Input streams with present and future but no past
- Functor: $DA = A^{\mathbb{N}} \quad (\cong A \times A^{\mathbb{N}})$

Comonads for attribute grammars

An attribute grammar is a CF grammar augmented with attributes and semantic equations.

Example: preorder numbering of the nodes

$$S^\ell \longrightarrow E$$

$$S^b \longrightarrow S_L^b S_R^b$$

$$S_L^b.\text{numin} = S^b.\text{numin} + 1$$

$$S_R^b.\text{numin} = S_L^b.\text{numout} + 1$$

$$S^\ell.\text{numout} = S^\ell.\text{numin}$$

$$S^b.\text{numout} = S_R^b.\text{numout}$$

Tree functions where the output at a position depends on the input at that position and around it (synthesized, inherited attributes).

Comonads for attribute grammars

Purely synthesized AG-s

• Functor: $DA = \text{Tree } A = \mu X. A \times (1 + X \times X)$

• Counit:

$$\begin{aligned} \varepsilon_A &: \text{Tree } A \rightarrow A \\ (a, s) &\mapsto a \end{aligned}$$

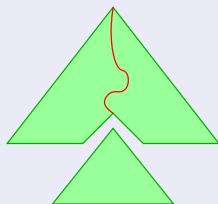
• Comultiplication:

$$\begin{aligned} \delta_A &: \text{Tree } A \rightarrow \text{Tree } (\text{Tree } A) \\ \delta_A(t) &= \begin{cases} (t, \text{inl}(*)), & \text{if } t = (a, \text{inl}(*)) \\ (t, \text{inr}(\delta_A(t_1), \delta_A(t_2))), & \text{if } t = (a, \text{inr}(t_1, t_2)) \end{cases} \end{aligned}$$

Comonads for attribute grammars

General AG-s

- Functor: $DA = (2 \times \text{Tree } A)^* \times \text{Tree } A$
- Path structure from the root to the focus and the local tree below the focus



Pre-[Cartesian closed] co-Kleisli categories

- Extending a pure language (the lambda calculus) with effect-constructs, we want the old constructs to remain and not to change their meaning too much.
- If D is a comonad on a Cartesian closed category \mathcal{C} , how much of that structure carries over to **CoKl**(D)?

Products

$$\begin{aligned} A \times^D B &=_{\text{df}} A \times B \\ \pi_0^D &=_{\text{df}} \pi_0 \circ \varepsilon \\ \pi_1^D &=_{\text{df}} \pi_1 \circ \varepsilon \\ \langle k_0, k_1 \rangle^D &=_{\text{df}} \langle k_0, k_1 \rangle \end{aligned}$$

Pre-[Cartesian closed] co-Kleisli categories

For (pre-)exponents we need some extra structure on a comonad:

$$\begin{array}{ccc}
 D((DA \Rightarrow B) \times A) & \xrightarrow{\langle D\pi_0, D\pi_1 \rangle} & D((DA \Rightarrow B)) \times DA \\
 \text{ev}^D \downarrow & & \downarrow (\varepsilon \times \text{id}) \\
 B & \xleftarrow{\text{ev}} & (DA \Rightarrow B) \times DA
 \end{array}$$

$$\frac{D(A \times B) \xrightarrow{k} C}{DA \xrightarrow{\wedge^D(k)} DB \Rightarrow C} \qquad \frac{DA \times DB \xrightarrow{?} D(A \times B) \xrightarrow{k} C}{DA \xrightarrow{\wedge(k\circ?) } DB \Rightarrow C}$$

Pre-[Cartesian closed] co-Kleisli categories

Definition

A comonad D on a [symmetric] [semi]monoidal cat. \mathcal{C} is said to be {lax/strong} [symmetric] [semi]monoidal, if it comes with

- a nat. {transf./iso.} $m : DA \otimes DB \rightarrow D(A \otimes B)$
- [and a nat. {transf./iso.} $e : I \rightarrow DI$]

behaving well wrt. $\alpha, [l, r,] [\gamma,] \varepsilon, \delta$.

Pre-exponents

Let D be a comonad on a Cartesian closed cat. \mathcal{C} . Assuming that D that is a {lax/strong} [symmetric] [semi]monoidal wrt. the $(1, \times)$ symmetric monoidal structure on \mathcal{C} , define this structure on

$$\begin{aligned} \mathbf{CoKl}(D): \quad A \Rightarrow^D B &=_{\text{df}} DA \Rightarrow B \\ \text{ev}^D &=_{\text{df}} \text{ev} \circ \langle \varepsilon \circ D\pi_0, D\pi_1 \rangle \\ \Lambda^D(k) &=_{\text{df}} \Lambda(k \circ m) \end{aligned}$$

Pre-[Cartesian closed] co-Kleisli categories

If D is strong monoidal, then $C \Rightarrow^D -$ is right adjoint to $- \times^D C$ and hence \Rightarrow^D is an exponent functor:

$$\frac{\frac{D(A \times C) \rightarrow B}{DA \times DC \rightarrow B}}{DA \rightarrow DC \Rightarrow B}$$

However, this seems rare in computational applications, $DA = A^{\mathbb{N}}$ being an atypical example.

Strong symmetric monoidal structure on streams

$$\begin{aligned} m & : A^{\mathbb{N}} \times B^{\mathbb{N}} \rightarrow (A \times B)^{\mathbb{N}} \\ (\alpha, \beta) & \mapsto \lambda n. (\alpha(n), \beta(n)) \end{aligned}$$

Pre-[Cartesian closed] co-Kleisli categories

More common is that a comonad is lax symmetric semimonoidal, eg $DA = A^+$, $DA = A^{\mathbb{N}} \times \mathbb{N}$.

Lax symmetric semimonoidal structure on $-^{\mathbb{N}} \times \mathbb{N}$

$$\begin{aligned} m & : (A^{\mathbb{N}} \times \mathbb{N}) \times (B^{\mathbb{N}} \times \mathbb{N}) \rightarrow (A \times B)^{\mathbb{N}} \times \mathbb{N} \\ ((\alpha, k_1), (\beta, k_2)) & \mapsto (\lambda n. (\alpha(n), \beta(n)), k_1) \end{aligned}$$

Then it suffices to have m satisfying $m \circ \Delta = D \Delta$, where $\Delta = \langle \text{id}, \text{id} \rangle : A \rightarrow A \times A$ is the semicomonoid structure on the objects of \mathcal{C} , to get that \Rightarrow^D is a weak exponent functor.

Comonadic semantics

Comonadic semantics is obtained by interpreting the lambda-calculus into **CoKI**(D) in the standard way.

Comonadic semantics

$$\begin{aligned} \llbracket A \times B \rrbracket^D &=_{\text{df}} \llbracket A \rrbracket^D \times^D \llbracket B \rrbracket^D &= \llbracket A \rrbracket^D \times \llbracket B \rrbracket^D \\ \llbracket A \Rightarrow B \rrbracket^D &=_{\text{df}} \llbracket A \rrbracket^D \Rightarrow^D \llbracket B \rrbracket^D &= D\llbracket A \rrbracket^D \Rightarrow \llbracket B \rrbracket^D \\ \llbracket (\underline{x})x_i \rrbracket^D &=_{\text{df}} \pi_i^D &= \pi_i \circ \varepsilon \\ \llbracket (\underline{x})\text{fst}(t) \rrbracket^D &=_{\text{df}} \pi_0^D \circ^D \llbracket (\underline{x})t \rrbracket^D &= \pi_0 \circ \llbracket (\underline{x})t \rrbracket^D \\ \llbracket (\underline{x})\text{snd}(t) \rrbracket^D &=_{\text{df}} \pi_1^D \circ^D \llbracket (\underline{x})t \rrbracket^D &= \pi_1 \circ \llbracket (\underline{x})t \rrbracket^D \\ \llbracket (\underline{x})(t_0, t_1) \rrbracket^D &=_{\text{df}} \langle \llbracket (\underline{x})t_0 \rrbracket^D, \llbracket (\underline{x})t_1 \rrbracket^D \rangle^D \\ &= \langle \llbracket (\underline{x})t_0 \rrbracket^D, \llbracket (\underline{x})t_1 \rrbracket^D \rangle \\ \llbracket (\underline{x})t u \rrbracket^D &=_{\text{df}} \text{ev}^D \circ^D \langle \llbracket (\underline{x})t \rrbracket^D, \llbracket (\underline{x})u \rrbracket^D \rangle^D \\ &= \text{ev} \circ \langle \llbracket (\underline{x})t \rrbracket^D, (\llbracket (\underline{x})u \rrbracket^D)^\dagger \rangle \\ \llbracket (\underline{x})\lambda x t \rrbracket^D &=_{\text{df}} \Lambda^D(\llbracket (\underline{x}, x)t \rrbracket^D) &= \Lambda(\llbracket (\underline{x}, x)t \rrbracket^D \circ m) \end{aligned}$$

Coeffect-specific constructs are interpreted specifically.

Comonadic semantics

- $\underline{x} : \underline{C} \vdash t : A$ implies $\llbracket (\underline{x})t \rrbracket^D : \llbracket \underline{C} \rrbracket^D \rightarrow^D \llbracket A \rrbracket^D$, but not all equations of the lambda-calculus are validated.
- Closed terms: Type soundness for $\vdash t : A$ says that $\llbracket t \rrbracket^D : 1 \rightarrow^D \llbracket A \rrbracket^D$, i.e., $D1 \rightarrow \llbracket A \rrbracket^D$, so closed terms are evaluated relative to a coeffect over 1.

In case of general or causal stream functions, this is a list over 1, the time from the start.

If D is properly (symmetric) monoidal (e.g., $(-)^{\mathbb{N}}$), we have a canonical choice $e : 1 \rightarrow D1$.

- Comonadic dataflow language semantics: The first-order language agrees perfectly with Lucid and Lustre by its semantics.

The meaning of higher-order dataflow computation has been unclear. We get a neat semantics from mathematical considerations (cf. Colaço, Pouzet's design with two flavors of function spaces).

Distributive laws

Definition

A **distributive law** of a monad (T, η, μ) over a comonad (D, ε, δ) is a natural transformation $\lambda_A : DTA \rightarrow TDA$ st.

$$\begin{array}{ccc} DTA & \xrightarrow{\lambda} & TDA \\ & \searrow \varepsilon & \downarrow T\varepsilon \\ & & TA \end{array} \qquad \begin{array}{ccc} DTA & \xrightarrow{\lambda} & TDA \\ \delta \downarrow & & \downarrow T\delta \\ D^2TA & \xrightarrow{D\lambda} & DTDA \xrightarrow{\lambda} TD^2A \end{array}$$

$$\begin{array}{ccc} DA & & \\ D\eta \downarrow & \searrow \eta & \\ DTA & \xrightarrow{\lambda} & TDA \end{array} \qquad \begin{array}{ccc} DT^2A & \xrightarrow{\lambda} & TDTA \xrightarrow{T\lambda} T^2DA \\ D\mu \downarrow & & \downarrow \mu \\ DTA & \xrightarrow{\lambda} & TDA \end{array}$$

Distributive laws

Clocked dataflow computation (partial-stream functions)

$$TA = 1 + A$$

$$DA = A^+$$

$$\lambda : (1 + A)^+ \rightarrow 1 + A^+$$

$$as \mapsto \begin{cases} \text{inl}(*) & \text{if last}(as) = \text{inl}(*) \\ \text{inr}([a_i \mid \text{inr}(a_i) \leftarrow as]) & \text{otherwise} \end{cases}$$

Distributive laws

BiKleisli category

Given a monad T and comonad D with a distributive law $\lambda : DTA \rightarrow TDA$, the biKleisli category $\mathbf{BiKI}(T, D)$ is defined as:

$$\begin{aligned} |\mathbf{BiKI}(T, D)| &=_{\text{df}} |\mathcal{C}| \\ \mathbf{BiKI}(T, D)(A, B) &=_{\text{df}} \mathcal{C}(DA, TB) \\ \text{id}^{D, T} &=_{\text{df}} \eta \circ \varepsilon \\ \ell \circ^{D, T} k &=_{\text{df}} \ell^* \circ \lambda \circ k^\dagger \end{aligned}$$

Distributive laws

If \mathcal{C} is Cartesian closed, T is strong, D is lax symmetric semimonoidal, $\mathbf{BiKI}(D, T)$ carries a pre-[Cartesian closed] structure:

Pre-[Cartesian closed] structure

$$\begin{aligned} A \times^{D, T} B &=_{\text{df}} A \times B \\ \pi_0^{D, T} &=_{\text{df}} \eta \circ \pi_0 \circ \varepsilon \\ \pi_1^{D, T} &=_{\text{df}} \eta \circ \pi_1 \circ \varepsilon \\ \langle k_0, k_1 \rangle^{D, T} &=_{\text{df}} \sigma_1^* \circ \sigma_0 \circ \langle k_0, k_1 \rangle \\ \\ A \Rightarrow^{D, T} B &=_{\text{df}} DA \Rightarrow TB \\ \text{ev}^{D, T} &=_{\text{df}} \text{ev} \circ \langle \varepsilon \circ D\pi_0, D\pi_1 \rangle \\ \Lambda^{D, T}(k) &=_{\text{df}} \eta \circ \Lambda(k \circ m) \end{aligned}$$

Future work

- Dual computational lambda-calculus / comonadic metalanguage.
- General recursion in coKleisli categories.
- Structured recursion/corecursion for dataflow computation.
- Dualization of call-by-name.
- Compilation of comonadic code to automata (cf. Hansen, Costa, Rutten).