

Trees, Spanning Trees and Subgraphs

Introduction



## Paths and Simple Paths

**Definition:** A *path* in an undirected graph G = (V, E) is a sequence of zero or more edges in G

$$(v_0, v_1), (v_1, v_2), (v_2, v_3), \dots, (v_{k-1}, v_k)$$

where the second vertex (shown) in each edge is the first vertex (shown) in the next edge.



The path shown above is a path from  $v_0$  (the first vertex in the first edge) to  $v_k$  (the second vertex in the final edge).

This is a *simple path* if  $v_0, v_1, \ldots, v_k$  are *distinct*.

## Goals for the Lecture:

- We will introduce a particular type of graph a *(free) tree* that will be used in definitions of graph problems, and graph algorithms, throughout the rest of this course
- Additional important definitions and graph properties will also be introduced

#### Paths and Cycles

# Paths and Simple Paths

# Cycles and Simple Cycles

**Definition:** A cycle (in an undirected graph G = (V, E)) is a path with length greater than zero from some vertex **to itself**:

**Definition:** The *length* of a path is the length of the *sequence* of edges in it.

Thus the path shown in the previous slide has length k.

**Definition:** An undirected graph G = (V, E) is a *connected* graph if there is a path from u to v, for *every* pair of vertices  $u, v \in V$ .



A cycle  $(v_0, v_1), (v_1, v_2), \dots, (v_{k-2}, v_{k-1}), (v_{k-1}, v_0)$  is a simple cycle if  $v_0, v_1, \dots, v_{k-1}$  are distinct.

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Trees Definition

A graph G = (V, E) is *acyclic* if it does not have any cycles.

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Paths and Cycles

Problem: There is No Completely Standard Terminology!

### **Problem with Terminology**

- Different references tend to use these terms differently!
- For example, in some textbooks, a simple cycle is considered to be a kind of *simple path*, and the definition of "cycle" given is the same as the definition of *simple cycle* given above
- Other references only call something a "path" if it is a *simple path*, as defined above; they only call something a "cycle" if it is a *simple cycle*; and they use the term *walk* to refer to the more general kind of "path" that is defined in these notes

**Consequence:** You should check the definitions of these terms in any other references that you use!

# Trees

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**Definition**: A *free tree* is a connected acyclic graph.



Frequently we just call a free tree a "tree."

• If we identify one vertex as the "root," then the result is the kind of "rooted tree" we have seen before.

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## **Properties 2**

## Consider graph G = (V, E):

- If G is connected then  $|E| \ge |V| 1$
- **2** If *G* is acyclic then  $|E| \leq |V| 1$
- **③** If G is connected and acyclic then |E| = |V| 1

See the lecture supplement for proofs.

Consider graph G = (V, E). We will use the following properties to characterize trees:

- If G is a tree then it has |V| 1 edges
- 2 An acyclic graph with |V| 1 edges is a tree
- **③** A connected graph with |V| 1 edges is a tree

See the lecture supplement for proofs.



Suppose G = (V, E) is as follows.



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- If G = (V, E) is a connected undirected graph, then a spanning tree of G is a subgraph  $\widehat{G} = (\widehat{V}, \widehat{E})$  of G such that
  - $\widehat{V} = V$  (so that  $\widehat{G}$  includes all the vertices in G)
  - $\widehat{E} \subseteq E$
  - $\widehat{G}$  is a tree.

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# Example Tree 1

# Example Tree 2

Is the following graph  $G_1 = (V_1, E_1)$  a spanning tree of G? Yes!



Is the following graph  $G_2 = (V_2, E_2)$  also a spanning tree of G? Yes!



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	Spanning Trees			
Example Tree 3				Subgraphs a

Is the following graph  $G_3 = (V_3, E_3)$  is also a spanning tree of G? No! Doesn't span G (vertex g missing)



and Induced Subgraphs

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Predecessor Subgraphs Subgraphs and Induced Subgraphs

Suppose G = (V, E) is a graph.

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- $\widehat{G} = (\widehat{V}, \widehat{E})$  is a *subgraph* of G if  $\widehat{G}$  is a graph such that  $\widehat{V} \subseteq V$  and  $\widehat{E} \subseteq E$
- $\widetilde{G} = (\widetilde{V}, \widetilde{E})$  is an *induced subgraph* of G if
  - $\widetilde{G}$  is a subgraph of G and, furthermore
  - $\widetilde{E} = \left\{ (u, v) \in E \mid u, v \in \widetilde{V} \right\}$ , that is,  $\widetilde{G}$  includes *all* the edges from *G* that it possibly could

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#### Predecessor Subgraphs Subgraphs and Induced Subgraphs

## Example

 $G_2$  is an *induced subgraph* of  $G_1$ .

 $G_3$  is a *subgraph* of  $G_1$ , but  $G_3$  is **not** an *induced subgraph* of  $G_1$ .



### Predecessor Subgraphs Predecessor Subgraphs

## Predecessor Subgraphs

Let G = (V, E) and let  $s \in V$ . Construct a subset  $V_p$  of V, a subset  $E_p$  of E, and a function  $\pi : V \to V \cup \{\text{NIL}\}$  as follows.

- Initially,  $V_p = \{s\}$ ,  $E_p = \emptyset$ , and  $\pi(v) = \text{NIL}$  for every vertex  $v \in V$ .
- The following step is performed, between 0 and |V| 1 times:
  - Pick some vertex u from the set  $V_p$ .
  - Pick some vertex v ∈ V such that v ∉ V<sub>p</sub> and (u, v) ∈ E. (The process must end if this is not possible to do.)
  - Set  $\pi(v)$  to be u, add the vertex v to the set  $V_p$ , and add the edge  $(u, v) = (\pi(v), v)$  to  $E_p$

Note that  $V_p \subseteq V$ ,  $E_p \subseteq E$ , and each edge in  $E_p$  connects pairs of vertices that each belongs to  $V_p$  each time the above (interior) step is performed — so that  $G_p = (V_p, E_p)$  is always a *subgraph* of G.

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Example		Example Predecessor Subgraph Property
		The graph $G_p = (V_p, E_p)$ that has been constructed is called a <i>predecessor</i> subgraph.
a b c d d e f f		Claim: Let $G_p = (V_p, E_p)$ be a predecessor subgraph of an undirected graph G. a) $G_p$ is a subgraph of G and $G_p$ is a tree. b) If $V_p = V$ then $G_p$ is a spanning tree of G.
		Proof.
a b c d e f g h i $\pi$ NIL a b a b e h e f		Part (a) is true because $ E_p  =  V_p  - 1$ , by the construction of $V_p$ and of $E_p$ , and $G_p$ is always connected, so $G_p$ is a tree, as well as a subgraph of $G$ . Part (b) now follows by the fact that $E_p$ is a subset of $E$ , so that $G_p$ is a subgraph of $G$ , and by the fact that $V_p = V$ .

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