

Data Science: Machine Learning: Tensorflow Neural Networks

**CPSC 501: Advanced Programming Techniques
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Jonathan Hudson, Ph.D
Assistant Professor (Teaching)
Department of Computer Science
University of Calgary

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MNIST

One MNIST Database

- Each image is a 28x28 array, flattened out to be a 1-d tensor of size 784



Model

- Input to model
- X: image of a handwritten digit
- Y: the digit value

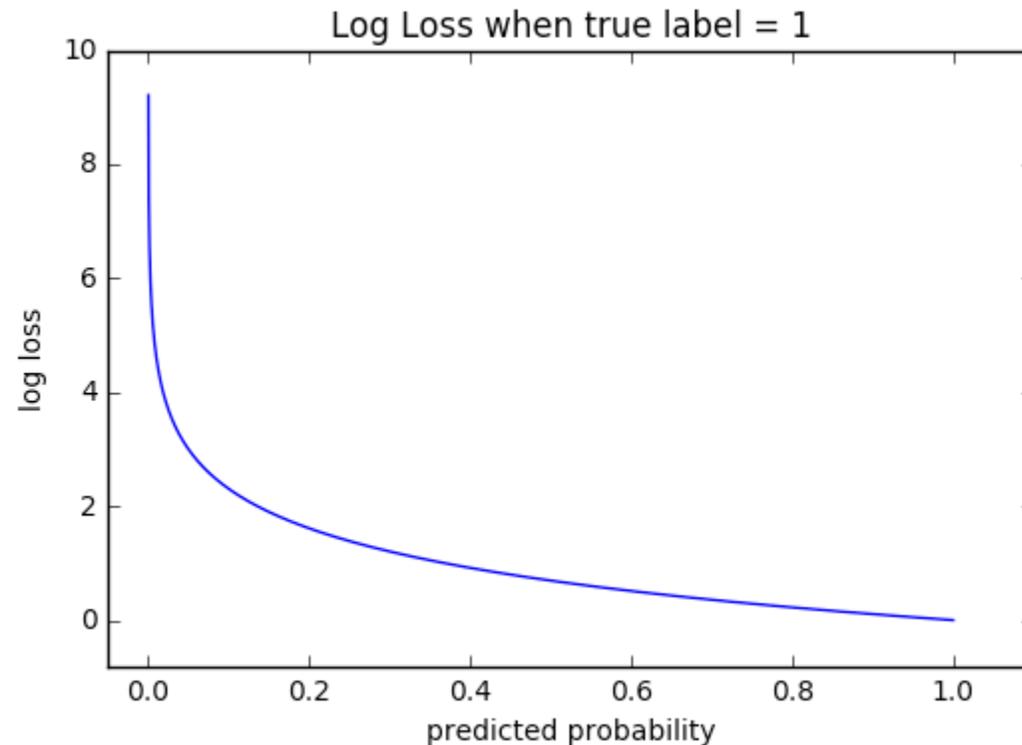
- Goal: trained model that recognizes the digit in the image

Model

- **Inference:** $Y_{\text{predicted}} = \text{softmax}(X * w + b)$
 - We want network that predicts 10 digits
 - We also want the sum of our probabilities across output layer to be 1
 - Sigmoid activation would give use between 0 and 1
 - Softmax goes step further and makes sure sum of the 10 probabilities are 1 in total

Model

- **Cross entropy loss: $-\log(Y_{\text{predicted}})$**
 - Made for measuring performance of models where output is 0 to 1



Pre-process

Process data

#TF2 Includes MNIST data already (mostly for learning purposes)

```
mnist = tf.keras.datasets.mnist
```

```
(x_train, y_train), (x_test, y_test) = mnist.load_data()
```

#We need to level color data to 0 to 1 range

```
x_train, x_test = x_train / 255.0, x_test / 255.0
```

#We are classifying digits 0 to 9

```
class_names = list(range(10))
```

Graph (Neural Network)

Phase 1: Assemble our graph

```
model = tf.keras.models.Sequential([
    tf.keras.layers.Flatten(input_shape=(28, 28)),
    tf.keras.layers.Dense(10, activation='softmax')
])
```

Two layers

1. First we flatten image 2d array to a 1d tensor input
2. Then we make a connection from every image spot to every 0-9 integer output spot

Optimizer

Specify loss function

```
model.compile(  
    optimizer=sgd,  
    loss='sparse_categorical_crossentropy',  
    metrics=['accuracy'])
```

Use 'sgd' optimizer

We'll discuss the loss function later in slides

Train

Train our model and evaluate it's quality

```
model.fit(x_train, y_train, epochs=5)
```

```
model_loss, model_acc = model.evaluate(x_test, y_test, verbose=2)
```

```
print(f"Model Loss: {model_loss*100:.1f}%")
```

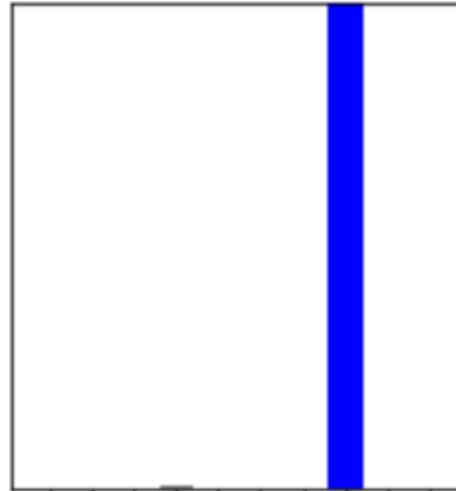
```
print(f"Model Accuray:{model_acc*100:.1f}%")
```

Output

Train our model and evaluate it's quality

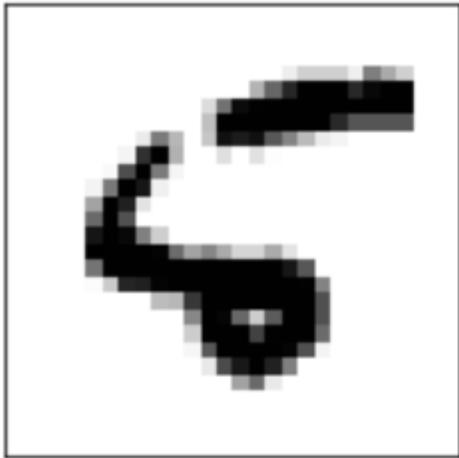


7 100% (7)

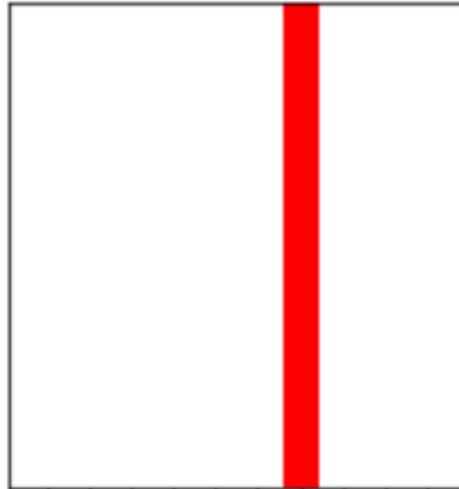


0 1 2 3 4 5 6 7 8 9

Train our model and evaluate it's quality



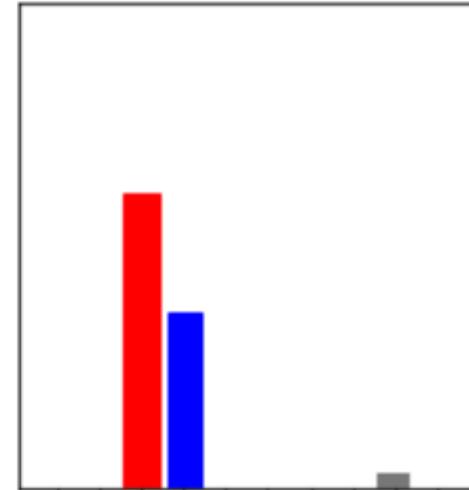
6 100% (5)



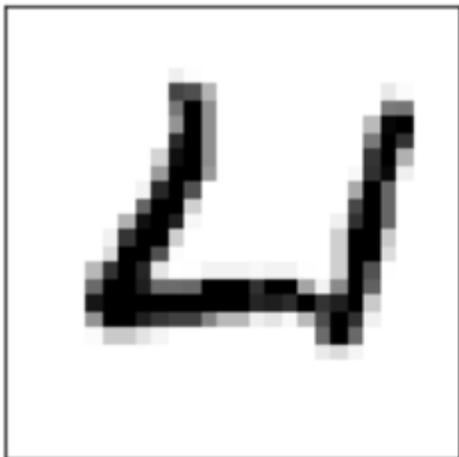
0 1 2 3 4 5 6 7 8 9



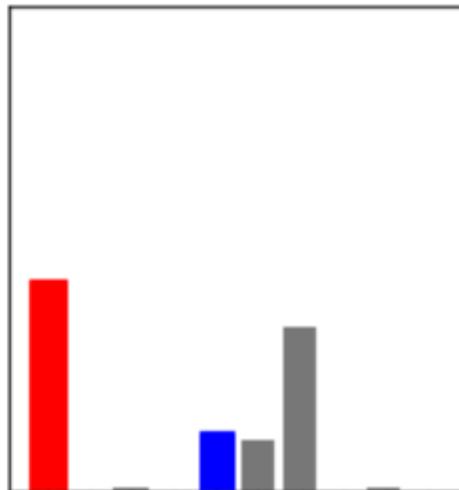
2 60% (3)



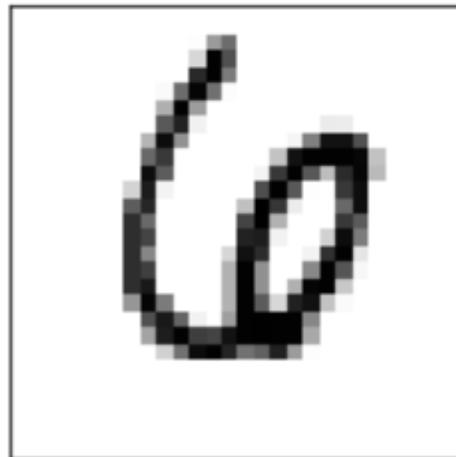
0 1 2 3 4 5 6 7 8 9



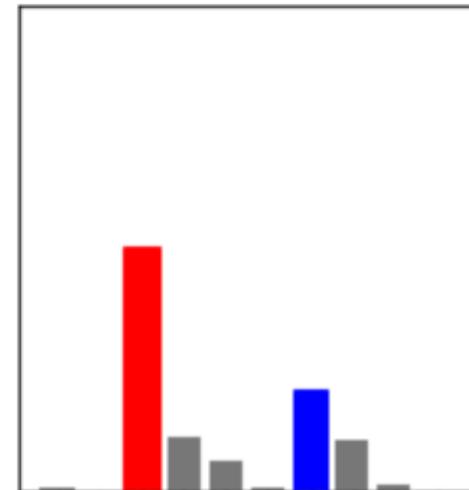
0 43% (4)



0 1 2 3 4 5 6 7 8 9



2 50% (6)



0 1 2 3 4 5 6 7 8 9

Saving and Loading

Save/Load our model

```
model.save('MINST.h5')
```

```
new_model = tf.keras.models.load_model('MINST.h5')
```

Can use this model exactly the same way we were the one we made and trained

How most apps works. Make model on the development end, spend a bunch of time testing it in dev, once the accuracy is good see if size/speed can be optimized, dump into production as finished product

Validate?

Splitting data?

- Why did we do this

```
(x_train, y_train), (x_test, y_test) = mnist.load_data()
```

- In some cases a neural network (other other model) might learn exactly what input maps to what output. Which would mean 100% performance on existing data.
- But in reality we generally want to predict things we don't have input for. 100% on known data, can sometimes result in algorithm that is much lower 66%! on new data. This is because the model didn't learn generalize patterns, but instead a mapping.
- Here we loaded a input set of data to train on, and a set to test on from MNIST.

```
(x_train, x_test, y_train, y_test) = train_test_split(X,y, random_state=0, train_size=0.5)
```

- Used to split any data into parts (here a 50% split)

Cross-validation

- If we have split data one technique to compare proposed models is cross-validation
- Split 50/50 then run two tests, each where data is input and other output, then reverse
- Often then combine the two measures to judge the model (average)
- X-fold validation is when you split data into more groups, where each subgroup takes turn as test data,
- sklearn has `cross_val_score(model, X, y, cv=5)` that will do this (here 5-fold)

Trade-offs

- Bias-Variance -> A more general model (like a single line of best fit, or a more varied model like a polynomial line), one might fit better but is realistically not a real model of data
- As model complexity increases it often gets easier to get a high training score, but often at a certain point the cross-validation score begins to decrease
- Larger data often helps us, more data will help a polynomial line from getting overfit as there may be enough data to keep it smoother and more realistic

Challenges

- Not enough data - easy for model to overfit and not generalize
 - “Unreasonable Effectiveness of Data” in many situations companies can often make their model better, less through design, and more through collecting more data (as often simple models are best anyway)
- Non-representative training data =- if your model has holes it will predict right over them. If you sample larger data (too little -> sample noise, too much -> sample bias)
- Poor-quality data - garbage in -> garbage out
- Irrelevant features – if you have bunch of features which are the same thing, the model will bias towards just them, can limit features, create new ones, or gather data with better features
- Overfitting/Underfitting - next

Dropout

Overfit/Underfit

- An example of overfit is the polynomial model that can perfectly match data, but forgoes actually trying to be a model that data fits in
- I.e. given enough time many neural networks can learn data perfectly (especially low input quantity data)
- Underfit is when your model is too simple – this is less a problem with neural networks (unless not given enough training time due to data being too large), however an example is trying to fit non-linear data to a linear model

Dropout

- During training, some number of layer outputs are randomly ignored or “dropped out.”
- the layer look-like and be treated-like a layer with a different number of nodes and connectivity to the prior layer
- In effect, each update to a layer during training is performed with a different “view” of the configured layer.

Dropout

- Dropout has the effect of making the training process noisy, forcing nodes within a layer to probabilistically take on more or less responsibility for the inputs.
- Makes it hard for network to overfit, it can't focus on creating singular paths for singular inputs to the trained output, has to try and represent the pattern

Dropout

- One gain is that each training step is faster
- Generally takes longer to train as less error updating is done (some nodes are idle each execution)
- Sometimes you need bigger network than you had previously

- Often larger dropout rates earlier (in CNN think of this is that we want to ignore little tiny features earlier on)
- Often lower dropout rates later (in CNN think of this as that we've made more complex ideas, they are less likely to be overfitted)

Learning Rate

Learning Rate

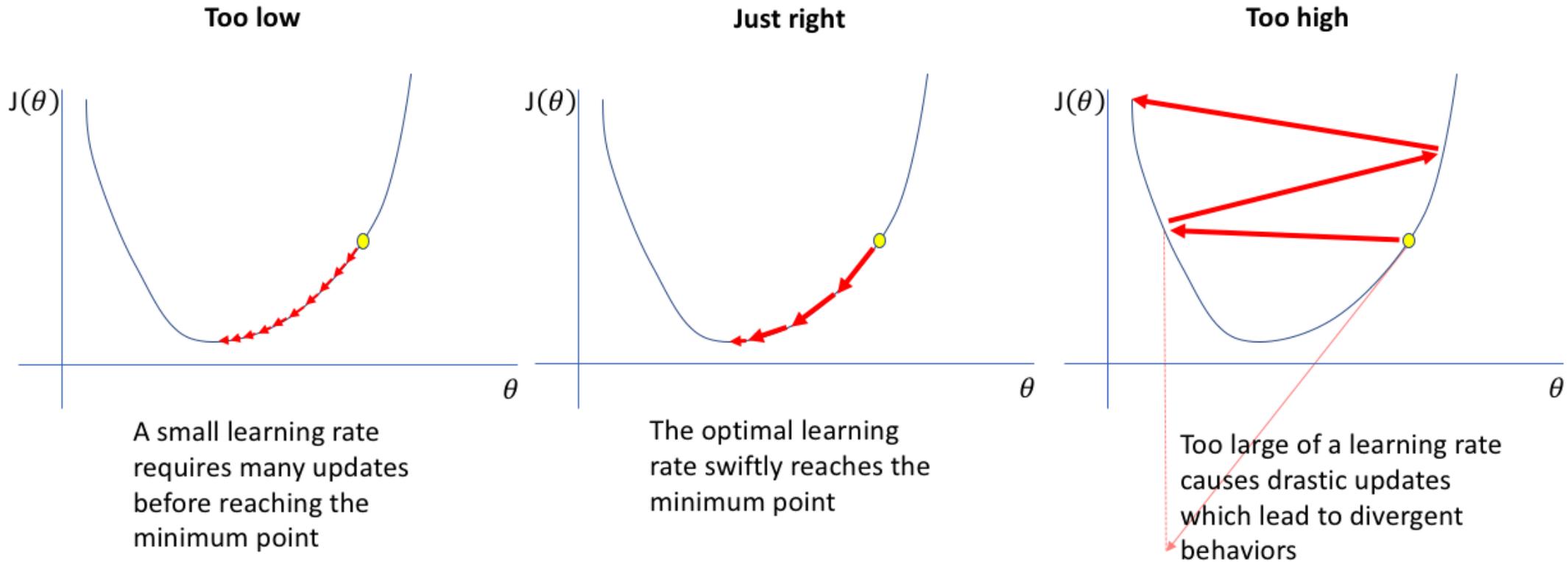
- Neural networks update their weights between neuron during backpropagation
- How large this update can be is dependant on the learning rate
- A high learning rate means they update the value by a large amount, a low learning rate means a small adjustment

Learning Rate

$$\theta_i := \theta_i - \alpha \frac{\partial J(\theta_i)}{\partial \theta_i}$$

- Alpha is the learning rate
- J is the loss function
- You can see the derivative of the loss function/ the current weight (the activation function) being the ratio of update

Learning Rate



A small learning rate requires many updates before reaching the minimum point

The optimal learning rate swiftly reaches the minimum point

Too large of a learning rate causes drastic updates which lead to divergent behaviors

Learning Rate Decay

- Start with large learning rate and then reduce it over time

`initial_learning_rate = 0.1`

```
lr_schedule = tf.keras.optimizers.schedules.ExponentialDecay(  
    initial_learning_rate,  
    decay_steps=100000,  
    decay_rate=0.96,  
    staircase=True)
```

Learning Rate Decay

- Start with large learning rate and then reduce it over time

```
model.compile(  
    optimizer=tf.keras.optimizers.SGD(learning_rate=lr_schedule),  
    loss='sparse_categorical_crossentropy',  
    metrics=['accuracy'])  
model.fit(data, labels, epochs=5)
```

Keras Optimizers

SGD

- stochastic gradient descent, update based on learning rate multiplied by gradient (derivative ratio of loss and activation)

Adagrad

- SGD that adapts learning rates for parameters based on how often they are update

Adadelta

- robust Adagrad (adapts learning rate itself based on moving window), no need for learning rate to be set

Optimizers

Keras Optimizers

RMSprop

- maintain moving average of square of gradients, divide gradient by this square when considering an update

Adam

- SGD based on adaptive estimation of first and second –order moments (average and variance)
- basically RMSprop with momentum

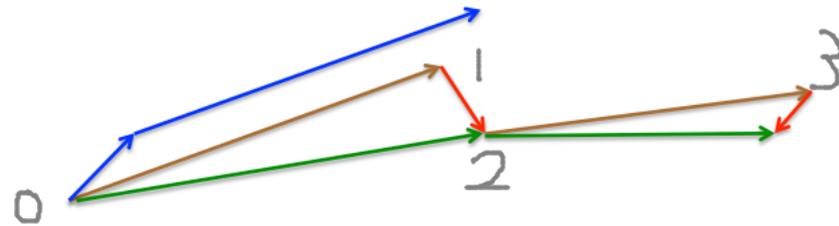
Keras Optimizers

Adamax – Adam but based on infinity norm

Nadam – like Adam with Nesterov momentum

A picture of the Nesterov method

- **First** make a big jump in the direction of the previous accumulated gradient.
- **Then** measure the gradient where you end up and make a correction.



brown vector = jump, red vector = correction, green vector = accumulated gradient

blue vectors = standard momentum

Ftrl – (newer ac

Loss Functions

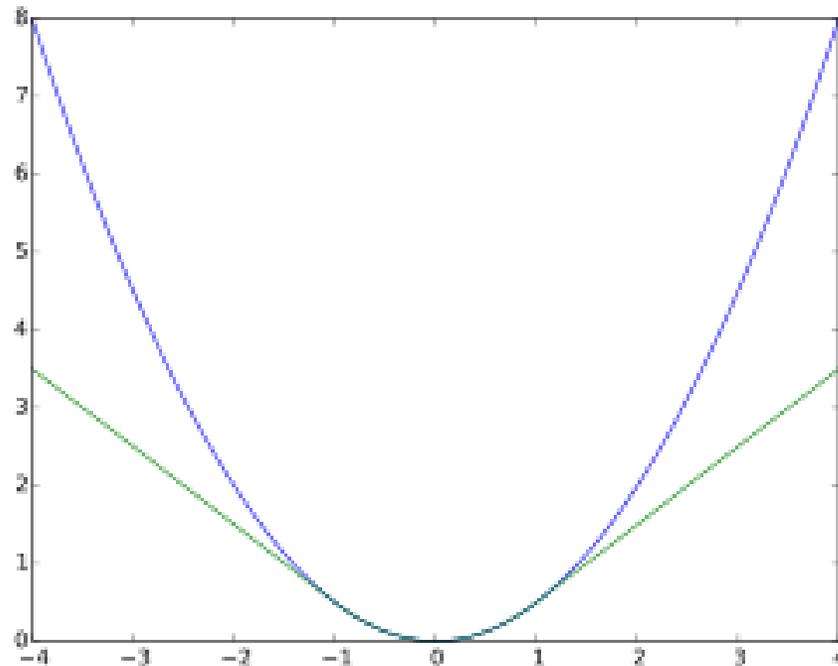
Keras loss functions – basic error

MeanSquaredError: $(y_{true} - y_{pred})^2$

Keras loss functions – basic error

MeanSquaredError: $(y_{true} - y_{pred})^2$

Huber: green



Keras loss functions – basic error

MeanSquaredLogarithmicError: $(\log(y_{true}) - \log(y_{pred}))^2$

MeanAbsoluteError: $|y_{true} - y_{pred}|$

MeanAbsolutePercentageError : $100 * \frac{|y_{true} - y_{pred}|}{y_{true}}$

Poisson: $y_{pred} - y_{true} * \log(y_{pred})$

KLDivergence (Kullback-Leibler): $y_{true} * \log(\frac{y_{true}}{y_{pred}})$

Keras loss functions (y_{true} and y_{pred})

CosineSimilarity: cosine similarity

Hinge: $\max(1 - y_{true} * y_{pred}, 0)$

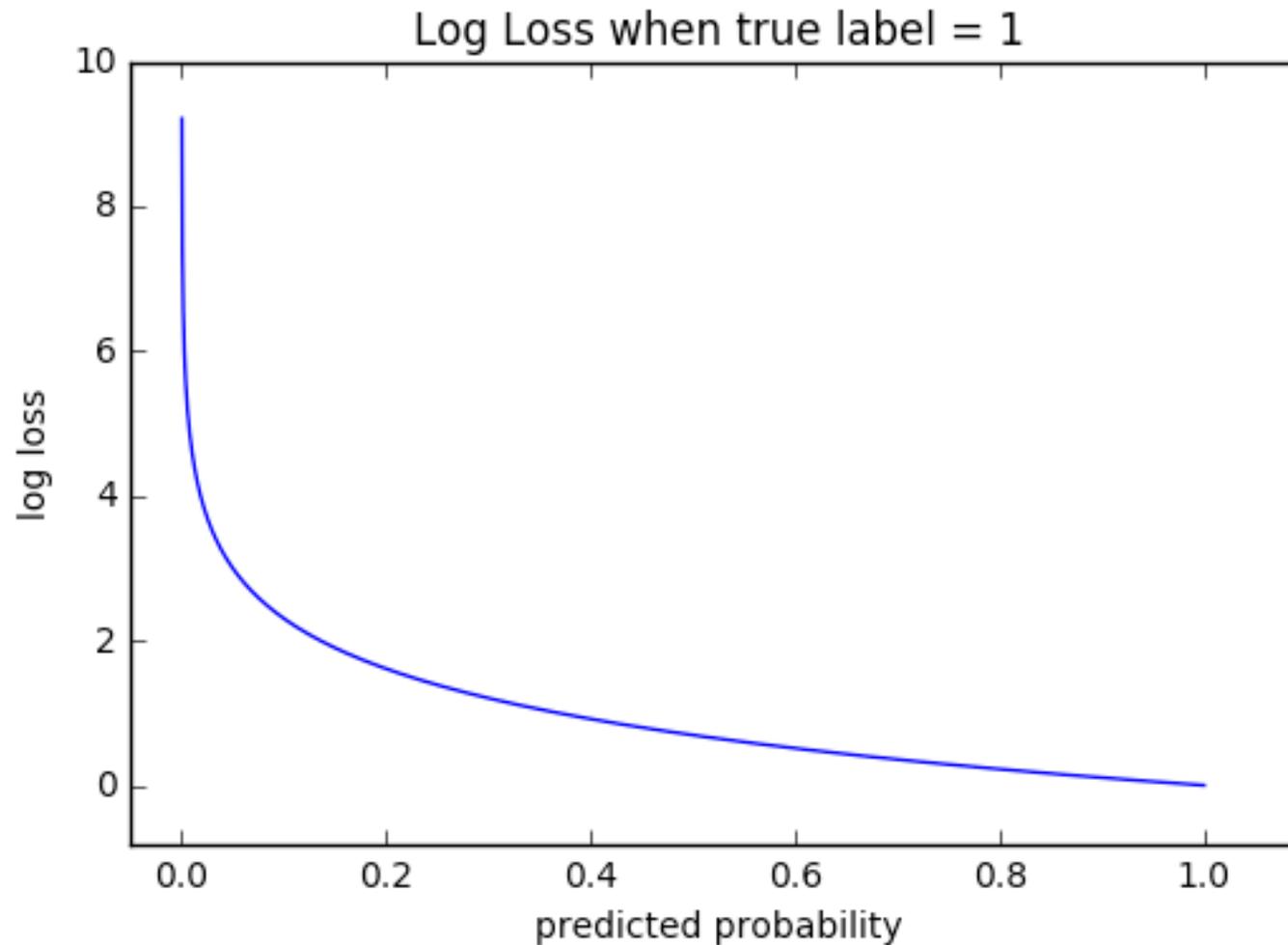
- Inputs expected to be -1 or 1

SquaredHinge: $\max(1 - y_{true} * y_{pred}, 0)^2$

CategoricalHinge: $\max(neg - pos + 1, 0)$

- where $neg = \sum(y_{true} * y_{pred})$ and $pos = \max(1 - y_{true})$

Keras loss functions – cross-entropy



Keras loss functions – cross-entropy

BinaryCrossentropy:

- only two label classes (0 and 1)

CategoricalCrossentropy:

- 2 or more labels in one-hot encoding 0 = [1,0,0,0] 1= [0,1,0,0] 2=[0,0,1,0],
3=[0,0,0,1]

SparseCategoricalCrossentropy:

- can use regular integer labels, 1,2,3,4

Onward to ... tensorflow with convolution NN.

Jonathan Hudson
jwhudson@ucalgary.ca
<https://pages.cpsc.ucalgary.ca/~jwhudson/>



UNIVERSITY OF
CALGARY