

# MONOIDAL STREAMS

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# PART 0: DATAFLOW PROGRAMMING

# MOTIVATION: DATAFLOW PROGRAMMING

Dataflow programming is a paradigm for repeated processes: every declaration is a sequence of values.

$fib = 0 \text{ FBY } (1 \text{ FBY WAIT } fib + fib)$   
 $nat = 0 \text{ FBY } (1 + nat)$

- Elegant recursive dataflow syntax.
- Signal flow, 'trace-like' diagrams.
- Semantics: causal streams for the cartesian case.

E.g. LUSTRE, LUCID.

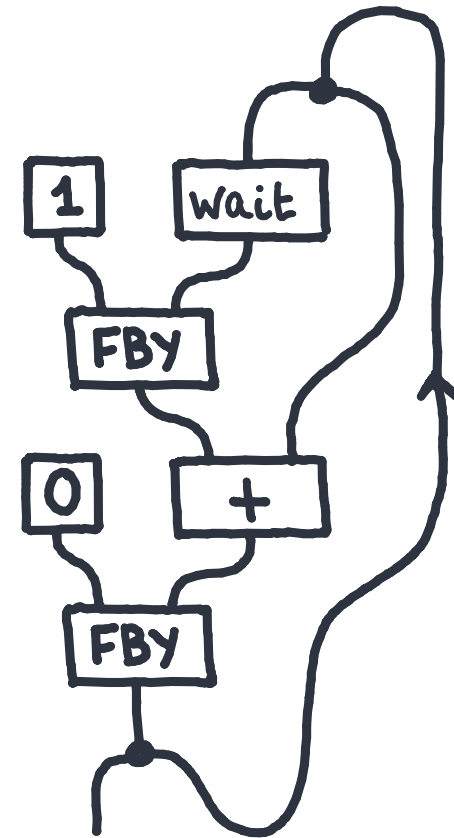


FIG. Signal flow graph.

# MOTIVATION: DATAFLOW PROGRAMMING

Dataflow programming is a paradigm for repeated processes: every declaration is a sequence of values.

"followed by"

"delayed stream"

$\text{fib} = 0 \text{ FBY } (1 \text{ FBY } \text{WAIT } \text{fib} + \text{fib})$

$\text{nat} = 0 \text{ FBY } (1 + \text{nat})$

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- Signal flow, 'trace-like' diagrams.
- Semantics: *causal streams* for the cartesian case.

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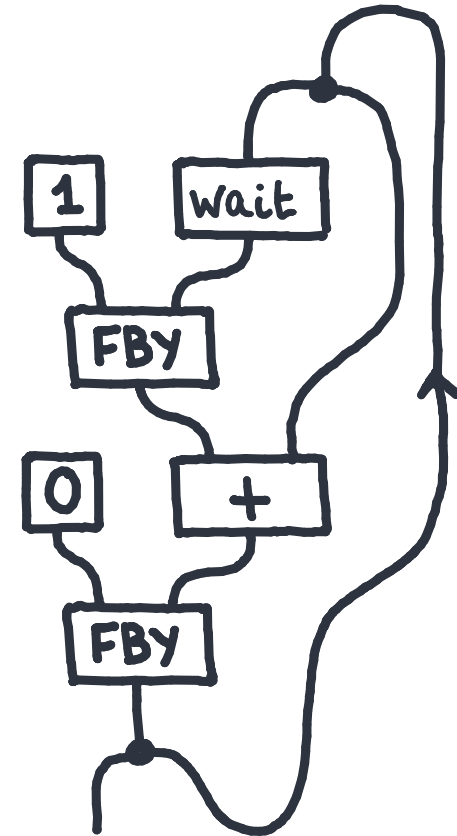


FIG. Signal flow graph.

# CAUSAL STREAM FUNCTIONS

DEFINITION. A **causal stream function**  $f: \mathbb{X} \rightarrow \mathbb{Y}$  is a family of functions

$$f_n: X_0 \times \dots \times X_n \rightarrow Y_n.$$

$$f_0: X_0 \rightarrow Y_0$$

$$f_1: X_0 \times X_1 \rightarrow Y_1$$

$$f_2: X_0 \times X_1 \times X_2 \rightarrow Y_2$$

...

These form a monoidal category, the **co Kleisli category** of the non-empty list monoidal comonad,

$$\mathbf{List}^+: [\mathbb{N}, \mathbf{SET}] \rightarrow [\mathbb{N}, \mathbf{SET}], \quad \mathbf{List}^+(\mathbb{X})_n = \prod_{i=0}^n X_i.$$

We have

- a delay functor taking  $\mathbb{X} = (X_0, X_1, X_2, \dots)$  into  $\partial \mathbb{X} = (1, X_0, X_1, \dots)$ ;
- a trace-like operator taking  $\partial S \otimes \mathbb{X} \rightarrow S \otimes \mathbb{Y}$  into  $\mathbb{X} \rightarrow \mathbb{Y}$ ;
- coalgebraic reasoning and coinductive arguments.



T. Uustalu, V. Vene. Comonadic Notions of Computation.  
D. Springer, S. Katsumata. Differentiable Causal Computations via Delayed Trace

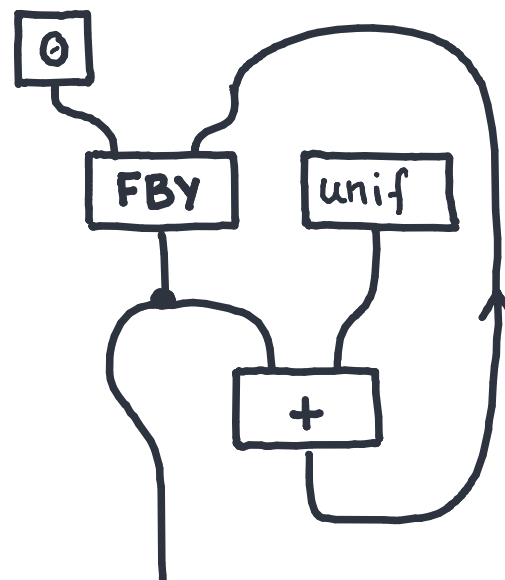
# MONOIDAL DATAFLOW PROGRAMMING

What about the non-cartesian case?

$$\text{walk} = 0 \text{ FBY UNIFORM } \{-1,1\} + \text{walk}$$

We imagine what the syntax should be, but, what should replace streams in the semantics?

These will be **monoidal streams**.



Can we extend the comonad to monoidal categories? **No**. We need a different solution.

THEOREM (DLdFR). The non-empty list functor  $\text{List}^+(X)_n = \prod_{i=0}^n X_i$  is a monoidal comonad **if and only if**  $(\otimes)$  is a cartesian product.

# MOTIVATION

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Today, given any symmetric monoidal category  $(\mathbb{C}, \otimes, \mathbb{I})$ , we will build a symmetric monoidal category of stream processes  $\text{Stream}(\mathbb{C})$  such that

- $\text{Stream}(\mathbb{C})$  has an id-on objs functor from  $[\mathbb{N}, \mathbb{C}]$ ;
- $\text{Stream}(\mathbb{C})$  has a delay monoidal functor,  $\partial$ ;
- $\text{Stream}(\mathbb{C})$  has delayed feedback taking  $\partial S \otimes X \rightarrow S \otimes Y$  into  $X \rightarrow Y$ ;
- $\text{Stream}(\mathbb{C})$  has a coalgebraic description;
- $\text{Stream}(\mathbb{C})$  is cartesian when  $\mathbb{C}$  is;
- $\text{Stream}(\text{SET})$  is the classical causal streams;
- $\text{Stream}(\text{STOCH})$  is causal discrete stochastic processes.
- $\text{Stream}(\mathbb{C})$  is symm. premonoidal, effectful or Freyd when  $\mathbb{C}$  is.

Three definitions in terms of universal properties, and three constructions.

# SYNOPSIS

Three definitions from universal properties, and three explicit constructions.  
Each one a quotient of the previous.

1. Intensional streams, a first naïve version. Fail to form a category.
2. Extensional streams, a free category with feedback.
3. Observational streams, definitive solution to a fixpoint equation.

Two known particular cases, and an avenue for more.

1. Cartesian monoidal streams  $(\text{Set}, x)$  are causal functions  
(as in Uustalu-Vene, Sprunger-Jacobs).
2. Stochastic streams  $(\text{KL}(D), x)$  are controlled stochastic processes  
(classical in the literature).
3. Kleisli streams of strong monads. Freyd categories in general.

Extra: implementing signal flow graphs and data-flow programs.



(Intensional)

PART 1 : MONOIDAL STREAMS

# STREAMS AND STREAM FUNCTIONS

"A **stream** of types  $A = (A_0, A_1, A_2, \dots)$  is an element of  $A_0$  together with a **stream** of types  $A^+ = (A_1, A_2, A_3, \dots)$ ."

$$S(A) \cong A_0 \times S(A^+).$$

# STREAMS AND STREAM FUNCTIONS

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$$S(A) \cong A_0 \times S(A^+).$$

By **Adamek's Theorem**, the candidate solution is

$$\lim_{n \in \mathbb{N}} (1 \leftarrow A_0 \leftarrow A_0 \times A_1 \leftarrow A_0 \times A_1 \times A_2 \leftarrow \dots) = \prod_{n=0}^{\infty} A_n ;$$

and it is a solution,  $A_0 \times \prod_{n=1}^{\infty} A_n \cong \prod_{n=0}^{\infty} A_n$ .

# STREAMS AND STREAM FUNCTIONS

"A stream function from  $X=(X_0, X_1, X_2, \dots)$  to  $Y=(Y_0, Y_1, Y_2, \dots)$  is a function  $X_0 \rightarrow Y_0$  communicating along a memory channel  $M$  with a stream function from  $X^+=(X_1, X_2, X_3, \dots)$  to  $Y^+=(Y_1, Y_2, Y_3, \dots)$ ."

$$T(X; Y) = \sum_{M \in \text{SET}} \text{hom}(X_0, M \times Y_0) \times T(M \times X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

By Adamek's Theorem, the candidate solution is

$$\lim_{n \in \mathbb{N}} (1 \leftarrow \text{hom}(X_0, Y_0) \leftarrow \text{hom}(X_0, Y_0) \times \text{hom}(X_0 \times X_1, Y_1) \leftarrow \dots) = \prod_{n=0}^{\infty} \text{hom}(X_0 \times \dots \times X_n, Y_n);$$

# MONOIDAL STREAMS

"A monoidal stream from  $X = (X_0, X_1, X_2, \dots)$  to  $Y = (Y_0, Y_1, Y_2, \dots)$  is a morphism  $X_0 \rightarrow Y_0$  communicating along a memory channel  $M$  with a monoidal stream from  $X^+ = (X_1, X_2, X_3, \dots)$  to  $Y^+ = (Y_1, Y_2, Y_3, \dots)$ ."

$$T(X; Y) = \sum_{M \in \text{SET}} \text{hom}(X_0, M \otimes Y_0) \times T(M \otimes X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

By Adamek's Theorem, the candidate solution is

$$\lim_{n \in \mathbb{N}} (1 \leftarrow \sum_n \sum_{M_0} \text{hom}(X_0, M_0 \otimes Y_0) \leftarrow \sum_{M_0 M_1} \text{hom}(X_0, M_0 \otimes Y_0) \times \text{hom}(M_0 \otimes X_1, M_1 \otimes Y_1) \leftarrow \dots) = \sum_{M: [\mathbb{N}, \mathbb{C}]} \prod_{n \in \mathbb{N}} \text{hom}(M_{n-1} \otimes X_n, M_n \otimes Y_n).$$

# MONOIDAL STREAMS

DEFINITION (DLdFR). An (intensional) **monoidal stream**  $X \rightarrow Y$  is a family of objects  $M_0, M_1, M_2, \dots$  and a family of morphisms  $f_n: M_{n-1} \otimes X_n \rightarrow M_n \otimes Y_n$ .

$$T(X, Y) = \sum_{M: [N, C]} \prod_{n \in \mathbb{N}} \text{hom}(M_{n-1} \otimes X_n, M_n \otimes Y_n).$$

THEOREM (DLdFR). The set of monoidal streams, depending on inputs and outputs, is the terminal fixpoint of

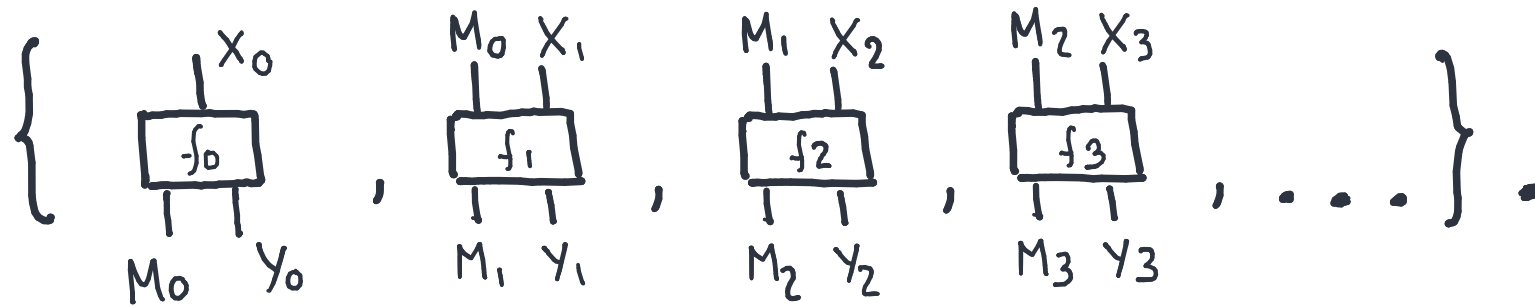
$$T(X, Y) = \sum_{M \in \text{SET}} \text{hom}(X_0, M \otimes Y_0) \times T(M \otimes X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

# MONOIDAL STREAMS

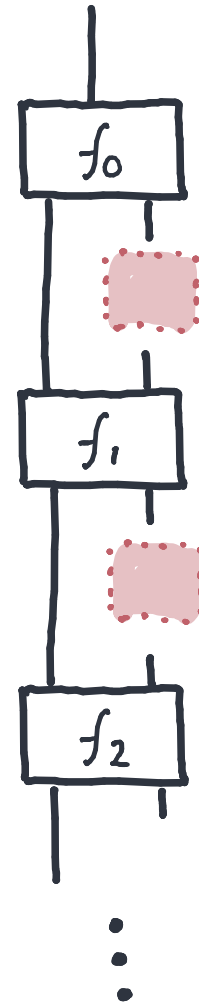
How to interpret a **monoidal stream**? In diagrams,

$$(f_n: M_{n-1} \otimes X_n \rightarrow M_n \otimes Y_n)$$

is



and yields the following "open diagram".



(Extensional)

## PART 2 : MONOIDAL STREAMS



# EXTENSIONAL STREAMS

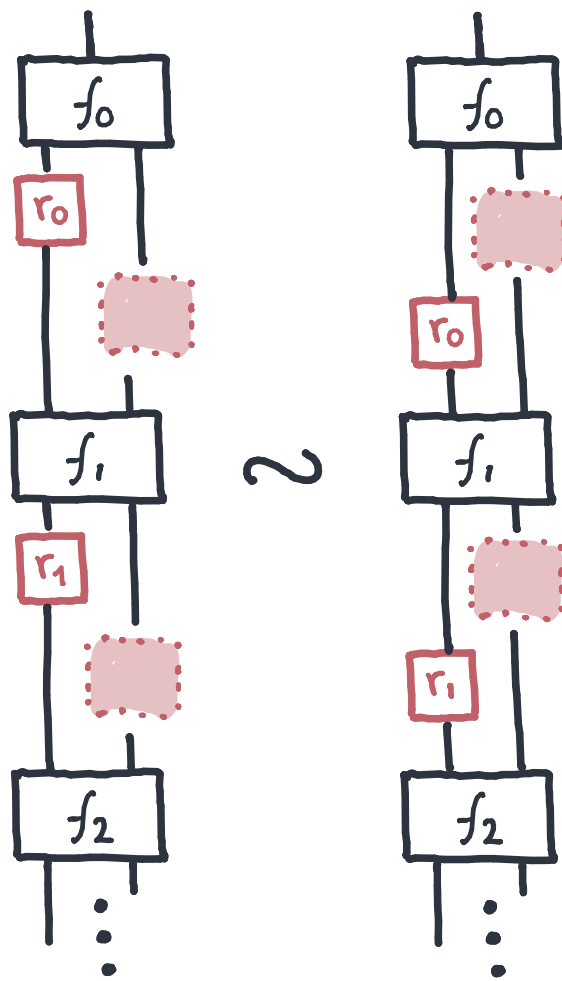
Monoidal streams are too explicit: e.g. having memories  $M_n = A_n \otimes (B_n \otimes C_n)$  is different from having memories  $M_n = (A_n \otimes B_n) \otimes C_n$ . This makes them fail to form a category.

DEFINITION. An (extensional) monoidal stream is an equivalence class of intensional streams under the minimal equivalence relation containing  $(\sim)$ .

$$\sum_{M: [N, C]} \prod_{n \in \mathbb{N}} \text{hom}(M_{n-1} \otimes X_n, M_n \otimes Y_n) / \langle \sim \rangle$$

$$\stackrel{=}{=} \int^{M: [N, C]} \prod_{n \in \mathbb{N}} \text{hom}(M_{n-1} \otimes X_n, M_n \otimes Y_n)$$

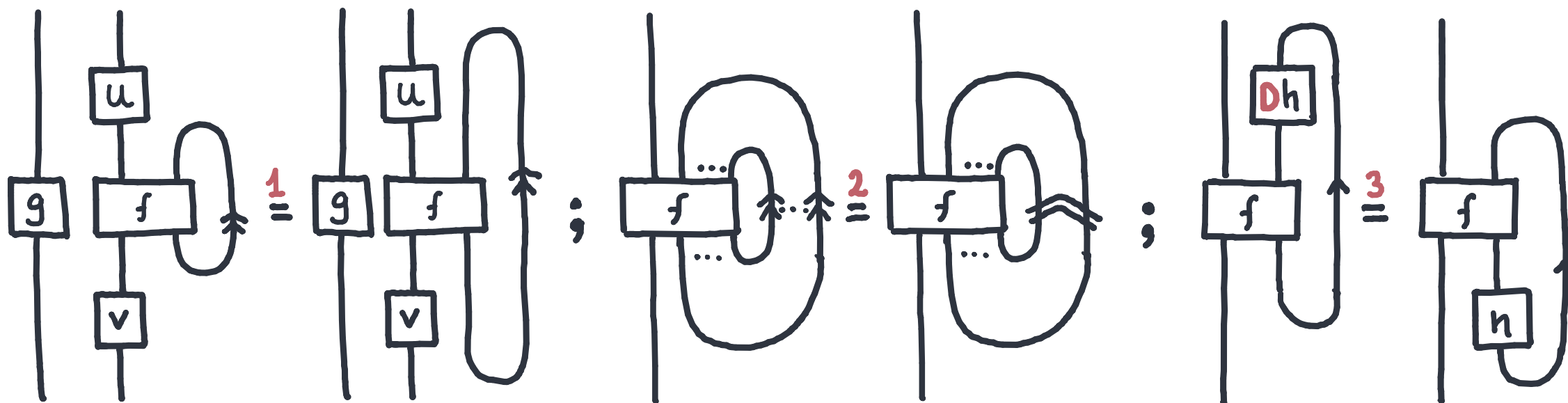
I like **coends**, but you may not; so let me justify them.



# FEEDBACK

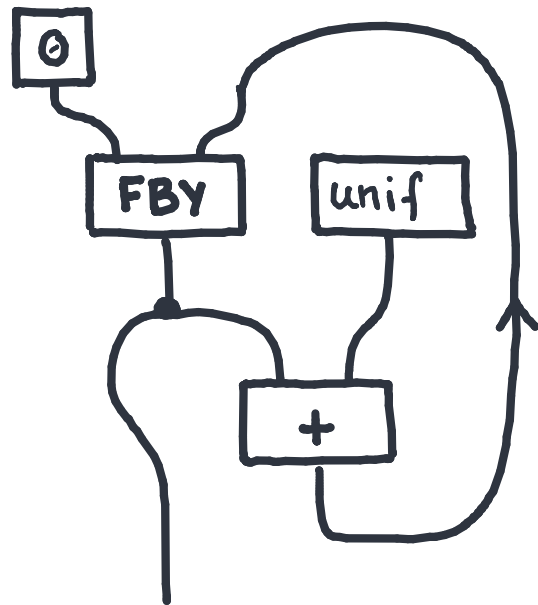
Feedback monoidal categories (Katis-Sabadini-Walters) axiomatize signal flow graphs using a guarded feedback operator  $\text{fbk}: \text{hom}(DS \otimes A, S \otimes B) \rightarrow \text{hom}(A, B)$ .

AXIOMS.

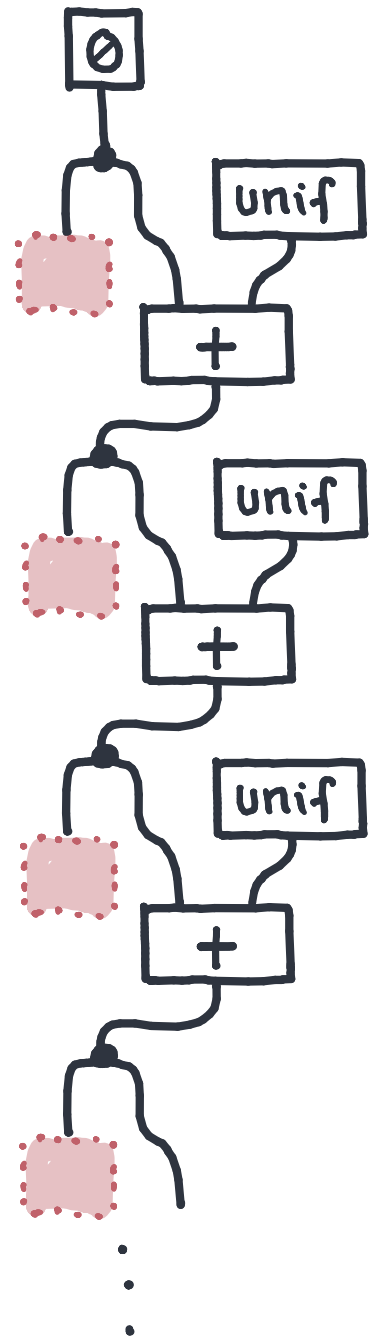


THEOREM (DLdFR). **Extensional streams** are the morphisms of the free category with feedback over  $\partial: [N, C] \rightarrow [N, C]$ ,  $\partial(A_0, A_1, A_2, \dots) = (I, A_0, A_1, \dots)$ .

# FEEDBACK

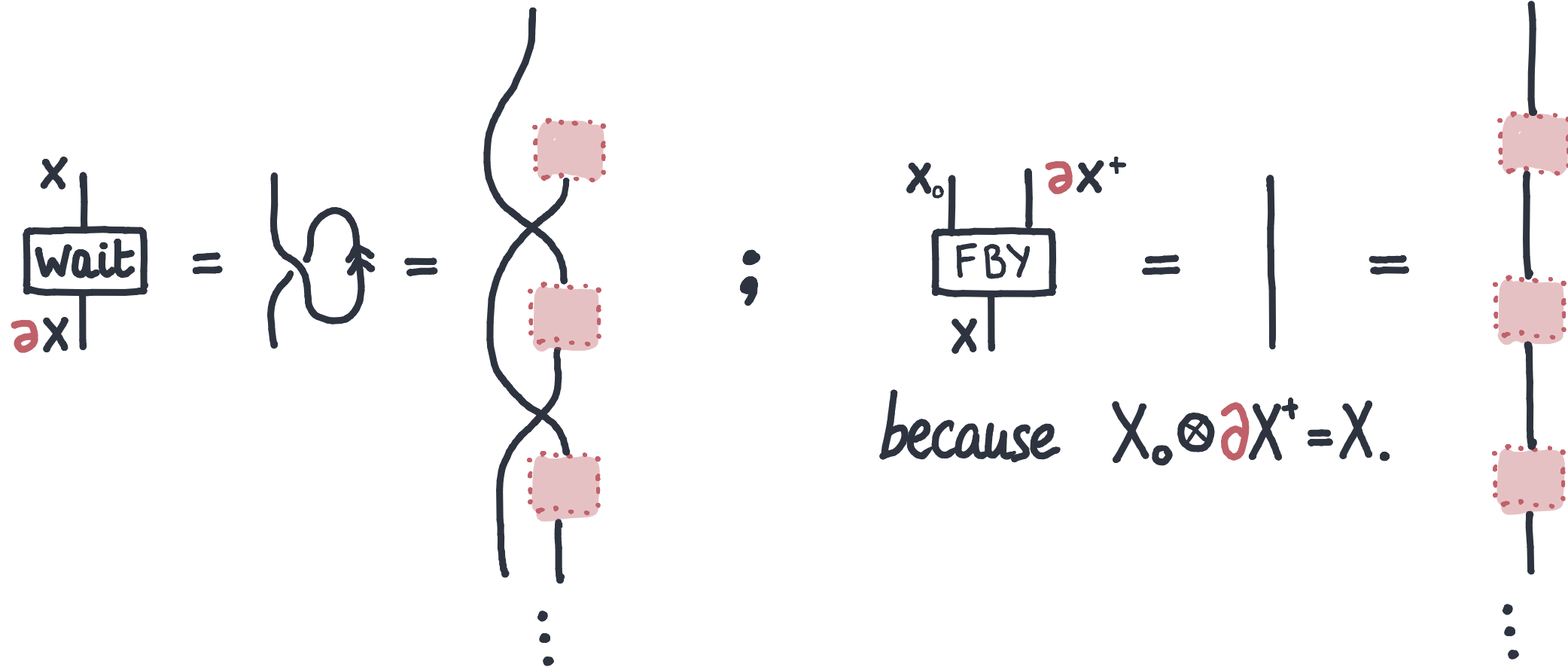


unroll  
→



# FEEDBACK

Dataflow syntax can be derived from [N.C] and feedback.



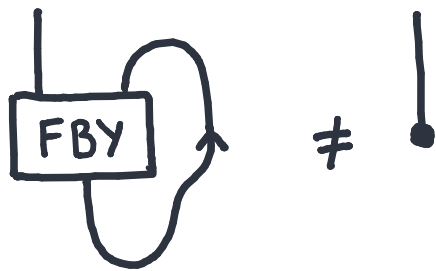
(Coinductive)

# PART 3: MONOIDAL STREAMS

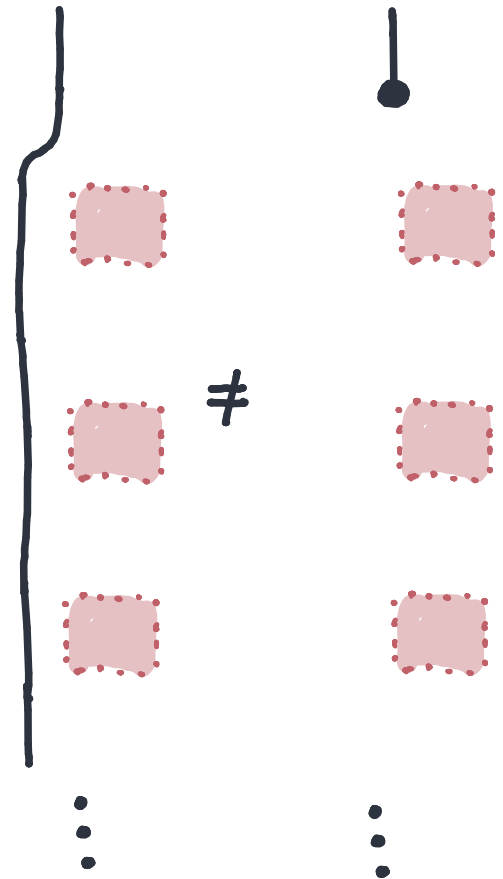
# OBSERVATIONAL EQUIVALENCE

So, we want, **at least**, extensional equivalence. Can we refine it?

Saving to memory without outputting is, **observationally**, the same as discarding. However, no amount of sliding will help us equating these two.



Two streams are **observationally equal** if their  $n$ th truncations can be made equal.



# COINDUCTIVE MONOIDAL STREAMS

Reasoning with monoidal streams in *well-behaved categories* is easy: they are a final coalgebra.

THEOREM (DLdFR). Monoidal streams (with observational eq.) are the final coalgebra of

$$Q(X, Y) \cong \int^{M: \mathbb{C}} \text{hom}(X_0, M \otimes Y_0) \times Q(M \otimes X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

DEFINITION (DLdFR). A *monoidal stream*  $f \in \text{Stream}(X_0, X_1, \dots; Y_0, Y_1, \dots)$  is

- a memory  $M(f) \in \mathbb{C}$
- a *now*( $f$ ) :  $X_0 \rightarrow M(f) \otimes Y_0$ ,
- and a *later*( $f$ )  $\in \text{Stream}(M \otimes X_1, X_2, \dots; Y_1, Y_2, \dots)$ .

Quotiented by  $f \approx g$ , meaning

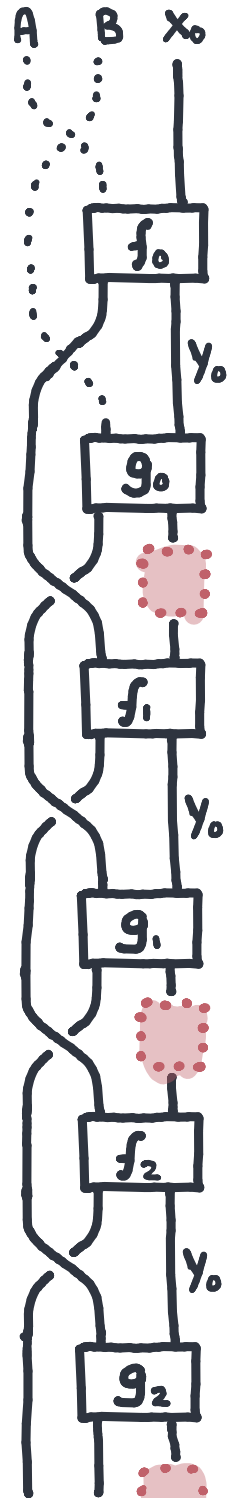
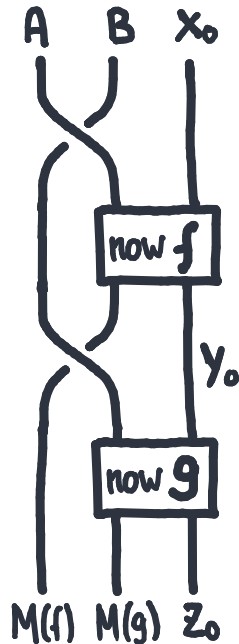
- the existence of  $r: M(f) \rightarrow M(g)$ ,

- such that  $\text{now}(f); (r \otimes \text{id}) = \text{now}(g)$ ,
- and such that  $\text{later}(f) \approx r \cdot \text{later}(g)$ .

# COINDUCTIVE MONOIDAL STREAMS

SEQUENTIAL COMPOSITION WITH MEMORY of  $f \in \text{Stream}(A \cdot X, Y)$  and  $g \in \text{Stream}(B \cdot Y, Z)$  is written as  $(f^A, g^B) \in \text{Stream}(A \otimes B \cdot X, Z)$ , and defined by

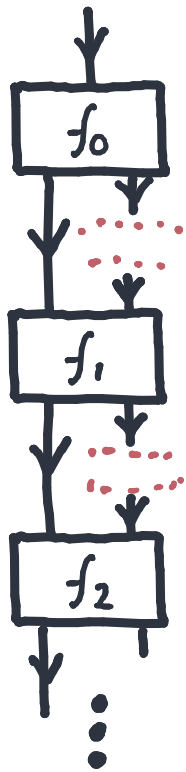
- $M(f^A, g^B) = M(f) \otimes M(g)$ ;
- $\text{later}(f^A, g^B) = \text{later}(f)^{M(f)}, \text{later}(g)^{M(g)}$ , by coinduction;
- $\text{now}(f^A, g^B) = \bullet$





# PART 4 : EXAMPLES

# CARTESIAN MONOIDAL STREAMS



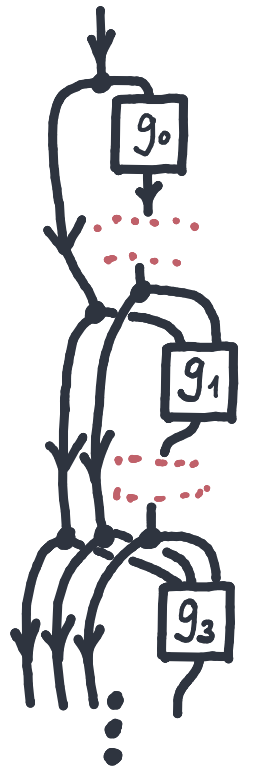
$S(X, Y)$

$$\cong \int^{M: \mathbb{C}} \text{hom}(X_0, M \times Y_0) \times S(M \times X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots)$$

$$\cong \int^{M: \mathbb{C}} \text{hom}(X_0, M \times Y_0) \times S(M \times X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots)$$

$$\cong \int^{M: \mathbb{C}} \text{hom}(X_0, M) \times \text{hom}(X_0, Y_0) \times S(M \times X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots)$$

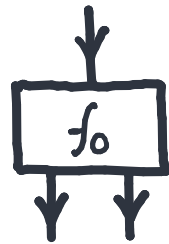
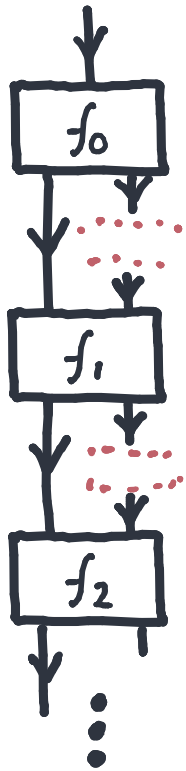
$$\cong \text{hom}(X_0, Y_0) \times S(X_0 \times X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots)$$



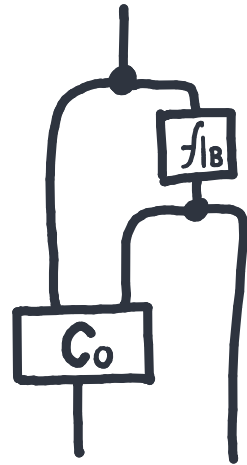
**THEOREM.** In cartesian monoidal categories, monoidal streams are *causal stream functions*.

# STOCHASTIC MONOIDAL STREAMS

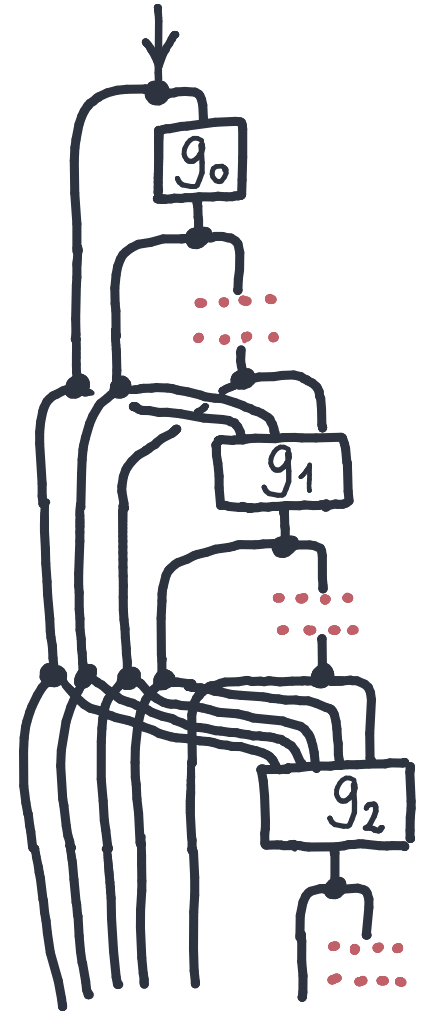
In **Markov categories** with conditionals, we can factor,



=



We use this to show that monoidal streams of stochastic functions are the same as **controlled stochastic processes**.



# STOCHASTIC PROCESSES

DEFINITION. A **controlled stochastic process**  $f: X \rightarrow Y$  is a family of stochastic functions  $f_n: X_0 \times \dots \times X_n \rightarrow D(Y_0 \times \dots \times Y_n)$  satisfying








$$\begin{array}{ccc} X_0 \times \dots \times X_{n+1} & \xrightarrow{f_{n+1}} & D(Y_0 \times \dots \times Y_{n+1}) \\ \downarrow \pi & & \downarrow D_n \\ X_0 \times \dots \times X_n & \xrightarrow{f_n} & D(Y_0 \times \dots \times Y_n) \end{array}$$

**causality:** the future  $X_{n+1}$  should not influence the past  $Y_0, \dots, Y_n$ .

THEOREM (DLdFR). Monoidal streams over  $KL(D)$  coincide with controlled stochastic processes.

PROOF. Non trivial. Somehow, the causality condition means that the family can be written *uniquely* as a monoidal stream.

# RELATED WORK

-  **Katis-Sabadini-Walters.** Categories with feedback, missing delay.
-  **Sprunger-Katsumata, Ghica-Kaye.** Finite memory or cartesian streams.
-  **Uustalu-Vene.** Cartesian streams, distributive laws for effects.
-  **Hughes-Paterson.** ArrowLoop are similar, but for traces.
-  **Carette-De Visme-Perdrix.** Syntax for similar streams.
-  **Many others.** Categorical dataflow. Functional reactive programming.
-  **Román.** Open diagrams via Coend Calculus.

END



# MONOIDAL STREAMS FOR DATAFLOW PROGRAMMING

ArXiv: 2202.02061, to be presented at LiCS'22.



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Giovanni de Felice

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Quantinuum



Mario Román

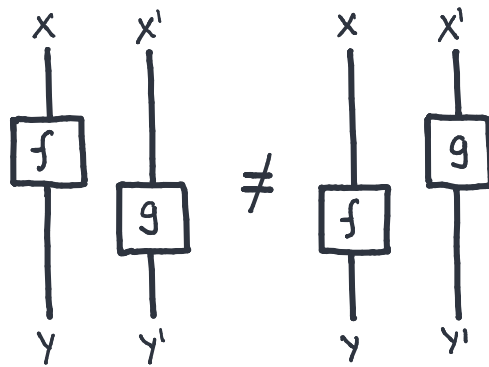
Tallinn University  
of Technology.

EXTRA : IMPLEMENTATION



# PREMONOIDAL CATEGORIES

A sym. premonoidal category  $(\mathbb{C}, \boxtimes, \mathbb{I})$  is a sym. monoidal category without the interchange law.



They usually have a family of "pure" morphisms that do satisfy interchange, forming a monoidal  $\mathbb{V}$ .

$$\mathbb{V} \longrightarrow \mathbb{C}$$

PURE  $\xrightarrow{\text{id-on-objects functor}}$  EFFECTFUL

This is called a Freyd category.

DEFINITION. The set of premonoidal streams in a Freyd category  $\mathbb{V} \rightarrow \mathbb{C}$  is the final fixpoint of

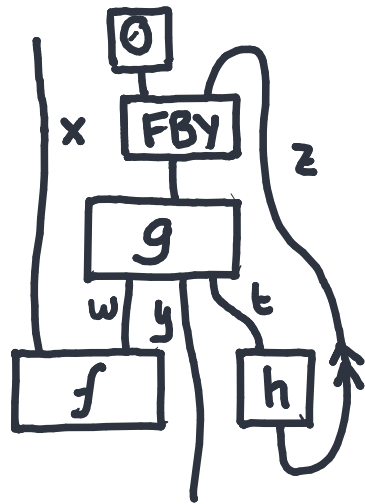
$$Q(X, Y) \cong \int^{M: \mathbb{V}} \text{hom}_{\mathbb{C}}(X_0, M \otimes Y_0) \times Q(M \otimes X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

Only pure morphisms should slide.

THEOREM. If  $\mathbb{V}$  is cartesian, and  $T$  is weakly cartesian then this final coalgebra is constructed by observational streams.

# IMPLEMENTATION

Type theory for sym. monoidal categories with feedback.



FBK z.

SPLIT  $g(0 \text{ FBY } h(z)) \rightarrow [w, y, t]$  IN

SPLIT  $f \times w \rightarrow []$  IN

RETURN y.

Obvious candidate: Haskell **Arrows** give notation for Set-based Freyd categories.

- **ArrowLoop** is for traced categories, in theory; it works for feedback.
- Github: [mroman42/arrow-streams](#).

EXTRA : COINDUCTION

# COINDUCTIVE MONOIDAL STREAMS

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DEFINITION (DLdFR). A monoidal stream  $f \in \text{Stream}(X_0, X_1, \dots; Y_0, Y_1, \dots)$  is

- a memory  $M(f) \in \mathbb{C}$
- a  $\text{now}(f) : X_0 \rightarrow M(f) \otimes Y_0$ ,
- and a  $\text{later}(f) \in \text{Stream}(M \otimes X_1, X_2, \dots; Y_1, Y_2, \dots)$ .

Quotiented by  $f \approx g$ , meaning

- the existence of  $r : M(f) \rightarrow M(g)$ ,
- such that  $\text{now}(f); (r \otimes \text{id}) = \text{now}(g)$ ,
- and such that  $\text{later}(f) \approx r \cdot \text{later}(g)$ .

# COINDUCTIVE MONOIDAL STREAMS

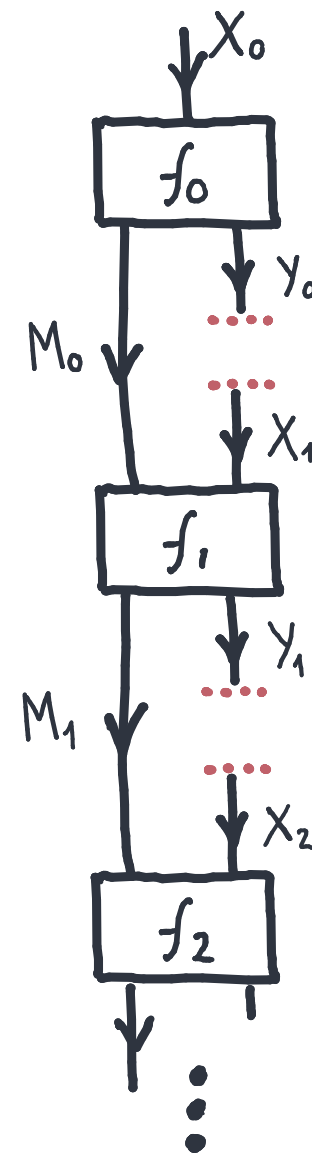
Reasoning with monoidal streams is easy: they are a final coalgebra.

$$S(X, Y) \cong \int^{M: \mathbb{C}} \text{hom}(X_0, M \otimes Y_0) \times S(M \otimes X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

Let me write  $X \in [N, \mathbb{C}]$  for  $X_0, X_1, \dots$ ; write  $X^+$  for  $X_1, X_2, \dots$ ; and write  $M \cdot X$  for  $M \otimes X_1, X_2, X_3, \dots$ ; the equation becomes

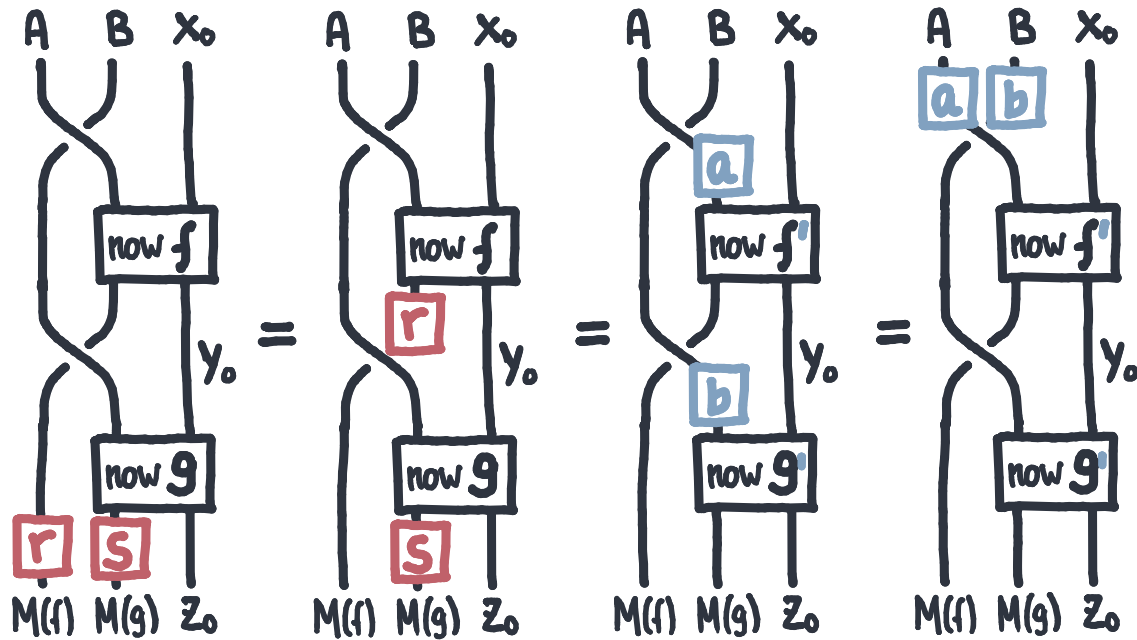
$$S(X, Y) \cong \int^{M: \mathbb{C}} \text{hom}(X_0, M \otimes Y_0) \times S(M \cdot X^+, Y^+).$$

The coend connects the  $M$  to the next step.



# COINDUCTIVE MONOIDAL STREAMS

SEQUENTIAL COMPOSITION is well-defined. Given generators  $f \stackrel{r}{\approx} a \cdot f'$  and  $g \stackrel{s}{\approx} b \cdot g'$ , we can show that  $(f^A \circ g^B) \stackrel{r \otimes s}{\approx} (a \otimes b) \cdot (f'^A \circ g'^B)$ .



By coinduction,

$$\text{later}(f)^{M(f)} \circ \text{later}(g)^{M(g)} \approx (r \otimes s) \cdot (\text{later}(f')^{M(f')} \circ \text{later}(g')^{M(g')}).$$

using  $\text{later}(f) \approx r \cdot \text{later}(f')$   
 $\text{later}(g) \approx s \cdot \text{later}(g')$ .

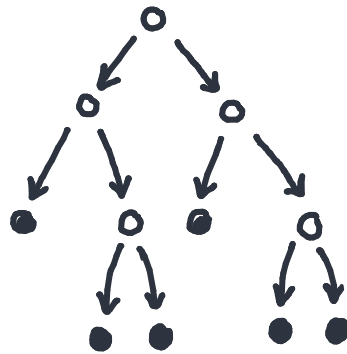
When  $a = \text{id}_A$ ,  $b = \text{id}_B$ , we have  $(f \stackrel{r}{\approx} f') \wedge (g \stackrel{s}{\approx} g') \Rightarrow f^A \circ g^B \stackrel{r \otimes s}{\approx} f'^A \circ g'^B$ .

# ALGEBRA



Finite lists.

$$L \cong A \times L + 1$$



Finite trees.

$$T \cong T^2 + 1$$



Natural numbers.

$$N \cong N + 1$$

Mathematics of syntax.

- Find the **initial** fixpoint of a functor,  $FX \cong X$ .
- Reason inductively.

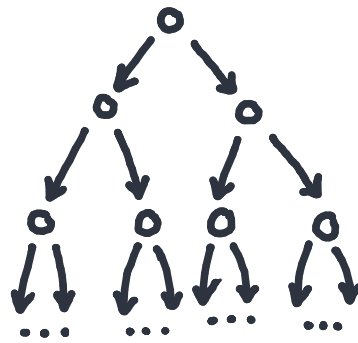
# COALGEBRA

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Infinite lists.

$$L \cong A \times L$$



Infinite trees.

$$T \cong T^2$$



Conatural numbers.

$$N \cong N + 1$$

Algebra of state and transitions.

- Find the **final** fixpoint of a functor,  $FX \cong X$ .
- Reason coinductively.



# COALGEBRA

THEOREM (LAMBEK). If the *final coalgebra* exists, it is a *final fixpoint*.

THEOREM (ADAMEK). If the following limit is a fixpoint, it is final.

$$\lim_{n \in \mathbb{N}} (1 \xleftarrow{!} F1 \xleftarrow{F!} FF1 \xleftarrow{FF!} FFF1 \xleftarrow{\dots} \dots)$$

$$\begin{array}{ccc} X & \xrightarrow{f} & U \\ \alpha \downarrow & \text{''} & \downarrow \cong \\ FX & \xrightarrow{Ff} & FU \end{array}$$

That is, to compute a fixpoint, repeatedly apply  $F$  and it will converge. Hopefully you will arrive to the fixpoint.

Initial algebras work too, but they will be less interesting.

# COINDUCTION

Reverse an infinite tree.

$$\text{reverse}(a; l, r) := (a, \text{reverse}(l), \text{reverse}(r))$$

$$\text{rev} \left( \begin{array}{c} \circ \\ \swarrow \quad \searrow \\ \Delta \quad \Delta \end{array} \right) = \text{rev}(\Delta) \quad \text{rev}(\Delta)$$

Reverse is self-inverse.

$$\text{rev} \left( \text{rev} \left( \begin{array}{c} \circ \\ \swarrow \quad \searrow \\ \Delta \quad \Delta \end{array} \right) \right) = \text{rev} \left( \text{rev}(\Delta) \quad \text{rev}(\Delta) \right) = \text{rev} \text{rev}(\Delta) \quad \text{rev} \text{rev}(\Delta) = \begin{array}{c} \circ \\ \swarrow \quad \searrow \\ \Delta \quad \Delta \end{array} .$$

Coinduction  
Hypothesis

EXTRA : OBSERVATIONAL STREAMS

# PROCESS INTERPRETATION

We think of functors  $\mathcal{C}^{\text{op}} * \mathcal{C} \rightarrow \text{SET}$  as indexing families of processes,  $P(M, N)$ , by **input**  $M$  and **output**  $N$ . How to plug the output to the input?

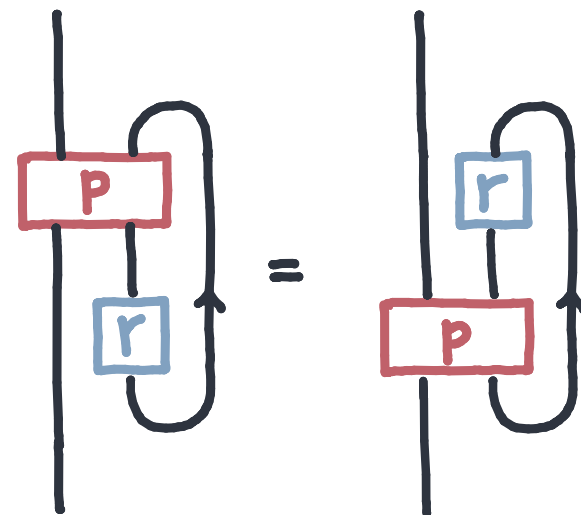
Given  $r: N \rightarrow M$ ,

- $P(\text{id}, r)(p) \in P(M, M)$ , translate **after reading**,
- $P(r, \text{id})(p) \in P(N, N)$ , translate **before writing**.

These are "morally the same": **dinaturally equivalent**.

We write the set  $\int^{X \in \mathcal{C}_{\text{obj}}} P(X, X)$  for  $\sum_{X \in \mathcal{C}_{\text{obj}}} P(X, X) / \sim$ , the **coend** of  $P$ ,

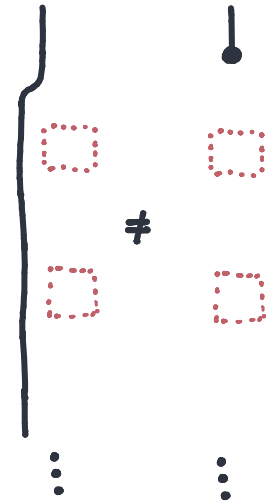
- $P(\text{id}, r)(p) \sim P(r, \text{id})(p)$ .



# OBSERVATIONAL EQUIVALENCE

So, we want, **at least**, extensional equivalence. Can we refine it?

Saving to memory without outputting is, **observationally**, the same as discarding. However, no amount of sliding will help us equating these two.



# OBSERVATIONAL EQUIVALENCE

So, we want, **at least**, extensional equivalence. Can we refine it?

**DEFINITION.** The  **$n$ -truncation** of an extensional stream  $\langle f_n \rangle$  is the first  $n$  components, up to any continuation.



Two streams are **observationally equal** if their  $n$ th truncations are equal. For instance,



This is not only a reasonable-sounding rule. This makes observational streams a canonical fixpoint.

# OBSERVATIONAL STREAMS

Intensional streams were the canonical fixpoint of the equation

$$T(X, Y) \cong \sum_{M \in \mathcal{C}} \text{hom}(X_0, M \otimes Y_0) \times T(M \otimes X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

**THEOREM (DLdFR).** *Observational streams*, in reasonably well-behaved categories (*productive*) are the canonical fixpoint of the equation

$$Q(X, Y) \cong \int^{M \in \mathcal{C}} \text{hom}(X_0, M \otimes Y_0) \times Q(M \otimes X_1, X_2, X_3, \dots; Y_1, Y_2, Y_3, \dots).$$

Why not in all categories? You could craft a category where there is no way to go from  $X_0$  to  $Y_0$  without knowing the future!

I.e. there are infinitely descending chains for a Loebner-like order  $f_n \sqsupseteq f_{n+1}$ .

# OBSERVATIONAL STREAMS

Why not in *all categories*? You could craft a category where there is no way to go from  $X_0$  to  $Y_0$  without knowing the future! Adamek could fail.

$$\int^{M:\mathbb{C}} \text{hom}(X_0, M \otimes Y_0) \times \lim^{n \in \mathbb{N}} \int^{M_1, \dots, M_n} \prod_{i=1}^n \text{hom}(M_{i-1} \otimes X_i, M_i \otimes Y_i)$$

$\cong$   $\checkmark$  fine

$$\int^{M:\mathbb{C}} \lim^{n \in \mathbb{N}} \int^{M_1, \dots, M_n} \text{hom}(X_0, M \otimes Y_0) \times \prod_{i=1}^n \text{hom}(M_{i-1} \otimes X_i, M_i \otimes Y_i)$$

$\cong$   $\times$  only discrete coproducts commute with connected limits

$$\lim^{n \in \mathbb{N}} \int^{M:\mathbb{C}} \int^{M_1, \dots, M_n} \text{hom}(X_0, M \otimes Y_0) \times \prod_{i=1}^n \text{hom}(M_{i-1} \otimes X_i, M_i \otimes Y_i)$$

I.e. there are infinitely descending chains for a Loebner-like order  $\boxed{f_n} = \boxed{f_{n+1}}$ .

Nothing to worry in semi cartesian, compact closed and freely generated monoidal.

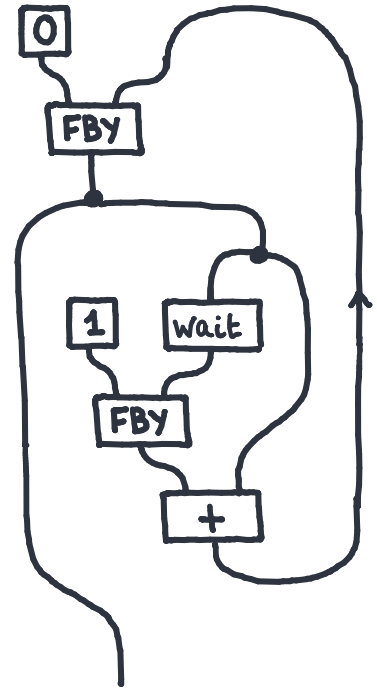


EXTRA : EXAMPLE

# MOTIVATION: DATAFLOW PROGRAMMING

$fib = 0$  FBY ( $fib + 1$  FBY WAIT  $fib$ )

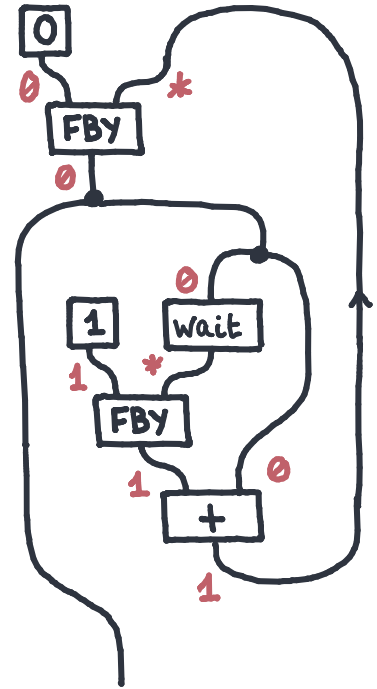
Time.	fib	WAIT(fib)	1FBYWAIT fib
0			
1			
2			
3			
4			
⋮			



# MOTIVATION: DATAFLOW PROGRAMMING

fib = 0 FBY (fib + 1 FBY WAIT fib)

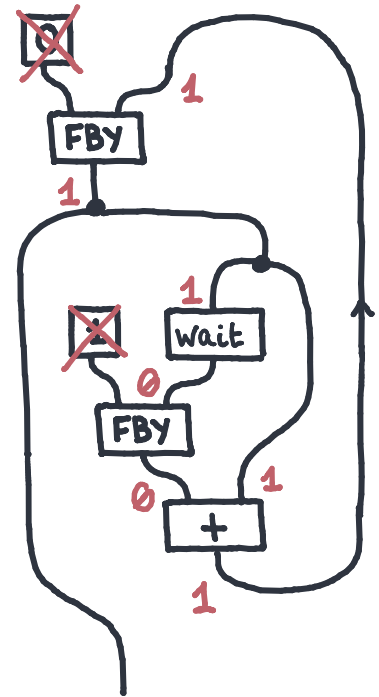
Time.	fib	WAIT(fib)	1FBYWAIT fib
0	0	*	1
1			
2			
3			
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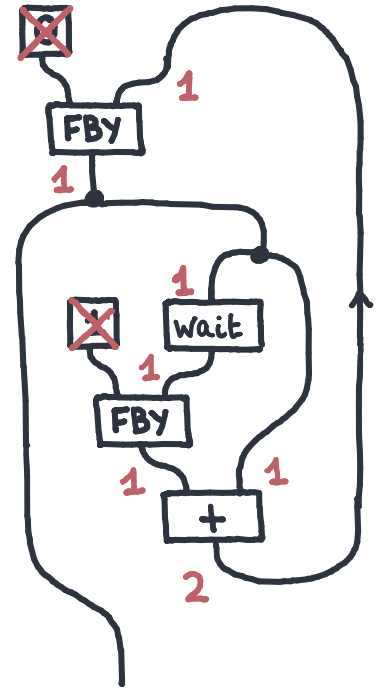
Time.	fib	WAIT(fib)	1FBYWAIT fib
0	0	*	1
1	1	0	0
2			
3			
4			
⋮			



# MOTIVATION: DATAFLOW PROGRAMMING

$fib = 0$   $FBY(fib + 1 FBY WAIT fib)$

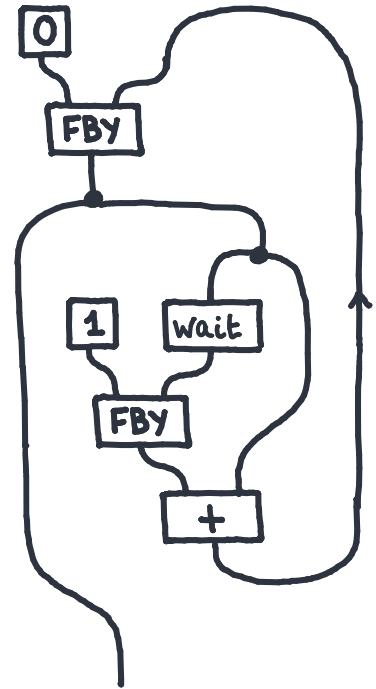
Time.	fib	WAIT(fib)	1FBYWAIT fib
0	0	*	1
1	1	0	0
2	1	1	1
3			
4			
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# MOTIVATION: DATAFLOW PROGRAMMING

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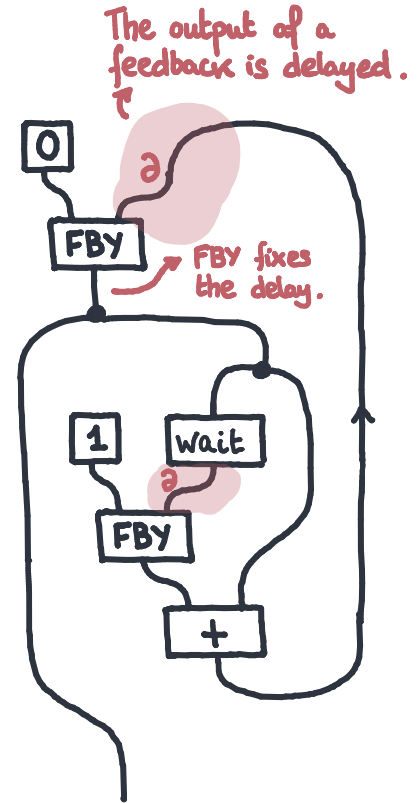
Time.	fib	WAIT(fib)	1FBYWAIT fib
0	0	*	1
1	1	0	0
2	1	1	1
3	2	1	1
4	3	2	2
⋮	⋮	⋮	⋮



# MOTIVATION: DATAFLOW PROGRAMMING

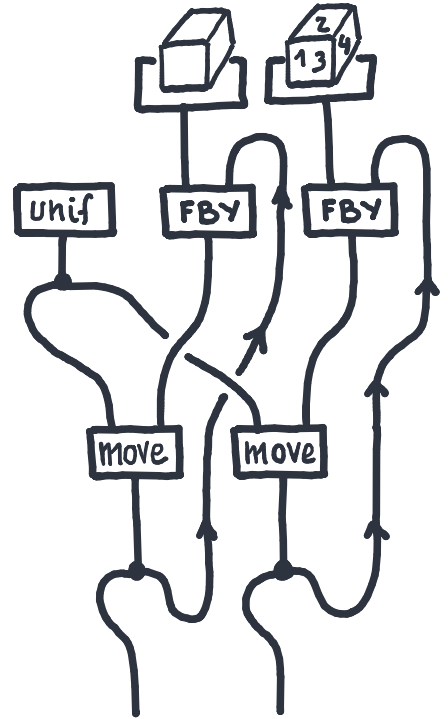
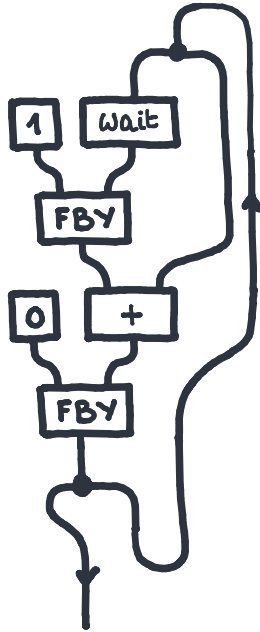
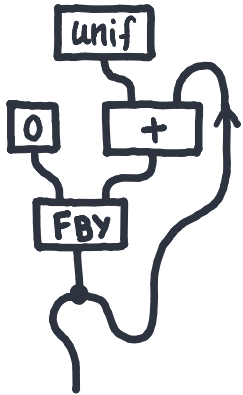
$fib = 0$  FBY ( $fib + 1$  FBY WAIT  $fib$ )

Time.	fib	WAIT(fib)	1FBYWAIT fib
0	0	*	1
1	1	0	0
2	1	1	1
3	2	1	1
4	3	2	2
⋮	⋮	⋮	⋮



How to ensure the output is well-defined? *Delayed types.*

# EXAMPLES





EXTRA : LENSES

# DINATURALITY AND COENDS

Given  $P: \mathcal{C}^{\text{op}} * \mathcal{C} \rightarrow \text{SET}$ , consider the set of all processes:  $\sum_{X \in \mathcal{C}_{\text{obj}}} P(x, x)$ .  
**Dinatural equivalence** is the smallest equivalence relation generated by

$$P(\text{id}, r)(p) \sim P(r, \text{id})(p).$$

We write the set  $\int^{X \in \mathcal{C}_{\text{obj}}} P(x, x)$  for  $\sum_{X \in \mathcal{C}_{\text{obj}}} P(x, x) / \sim$ , the **coend** of  $P$ .

"The coend,  $\int^{X \in \mathcal{C}_{\text{obj}}}$ , connects both  $X$ 's."

# MOTIVATION

In the process interpretation of monoidal categories, morphisms  $A \rightarrow B$  are processes with an **input**  $A$  and an **output**  $B$ .

However, most processes (servers, drivers, agents,...) are continuously taking inputs and producing outputs,



closed diagram vs



open, repeated diagram.



Román.<sup>[1]</sup> Open Diagrams via Coend Calculus. ACT'20.



Román.<sup>[2]</sup> Comb Diagrams for Discrete-Time Feedback. Preprint.

# MOTIVATION

**Lenses** can be used to describe a single exchange,

$$\mathbf{Lenses}(A_0, A_1; B_0, B_1) = \int^M \mathbf{hom}(A_0, B_0 * M) * \mathbf{hom}(M * A_1, B_1) \cong \mathbf{hom}(A_0, B_0) * \mathbf{hom}(A_1 * A_0, B_1);$$

but "fixpointing" the exchange, we get **causal stream functions**.

$$\mathbf{Stream}(A; B) = \int^M \mathbf{hom}(A_0, B_0 * M) * \mathbf{Stream}(M * A^+; B^+) = \mathbf{hom}(A_0, B_0) * \mathbf{Stream}(A_0 * A^+; B^+).$$

$$\mathbf{Stream}(A; B) \cong \mathbf{Optic}(\mathbf{Set}, \mathbf{Stream})((A_0, A^+); (B_0, B^+)).$$

Given the category **Stoch** of stochastic functions, the category of stochastic processes is the terminal fixpoint of

$$\mathbf{StochProc}(A; B) \cong \mathbf{Optic}(\mathbf{Stoch}, \mathbf{StochProc})((A_0, A^+); (B_0, B^+))$$

EXTRA : EXPRESSIVITY

# EXPRESSIVITY

Orthogonal to the rest of the paper. What is the expressivity of the feedback syntax over some generators? The  $St(\cdot)$  construction answers this.

- $\kappa$ -Linear functions: hidden multivariable linear recurrence equations.

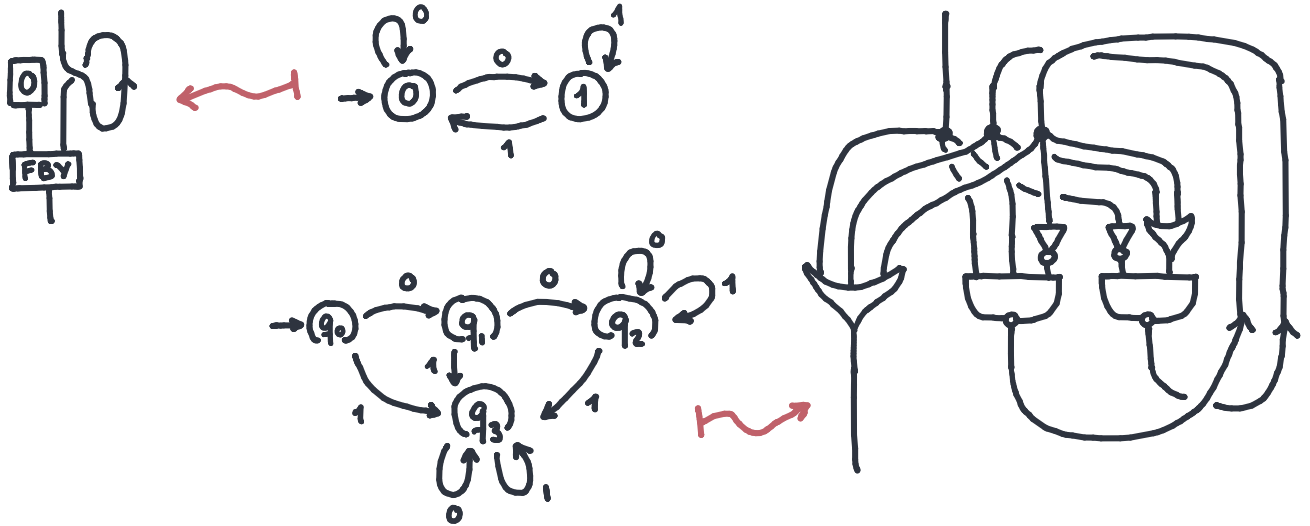
$$\begin{pmatrix} s_1 \\ \vdots \\ s_n \end{pmatrix}_{t+1} = \begin{pmatrix} \lambda_{11} & \cdots & \lambda_{1n} & \mu_{11} & \cdots & \mu_{1\kappa} \\ \vdots & & \vdots & \vdots & & \vdots \\ \lambda_{n1} & \cdots & \lambda_{nn} & \mu_{n1} & \cdots & \mu_{n\kappa} \end{pmatrix} \begin{pmatrix} s_1 \\ \vdots \\ s_n \\ a_1 \\ \vdots \\ a_\kappa \end{pmatrix}_t$$

$$\begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}_t = \begin{pmatrix} \varphi_{11} & \cdots & \varphi_{1n} & \psi_{11} & \cdots & \psi_{1\kappa} \\ \vdots & & \vdots & \vdots & & \vdots \\ \varphi_{n1} & \cdots & \varphi_{nn} & \psi_{n1} & \cdots & \psi_{n\kappa} \end{pmatrix} \begin{pmatrix} s_1 \\ \vdots \\ s_n \\ a_1 \\ \vdots \\ a_\kappa \end{pmatrix}_t$$

# EXPRESSIVITY

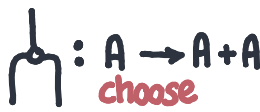
Orthogonal to the rest of the paper. What is the expressivity of the feedback syntax over some generators? The  $St(\cdot)$  construction answers this.

- Boolean circuits: controlled deterministic automata (w/boolean IO).



# EXPRESSIVITY

Monoidal streams over total relations can be interpreted as **Büchi automata**.



EXAMPLE:  $0^*1(0^*11)^w$

Park's equations.

$$\begin{aligned} X &\Rightarrow 0X + 1Y \\ Y &\doteq Z \\ Z &\Rightarrow 0Z + 1W \\ W &\Rightarrow 1Y \end{aligned}$$

